

Quantum Gravity and Cosmology 2024

Probing Gravity via Gauge Theory

— Recent progress on color-kinematics duality and double copy

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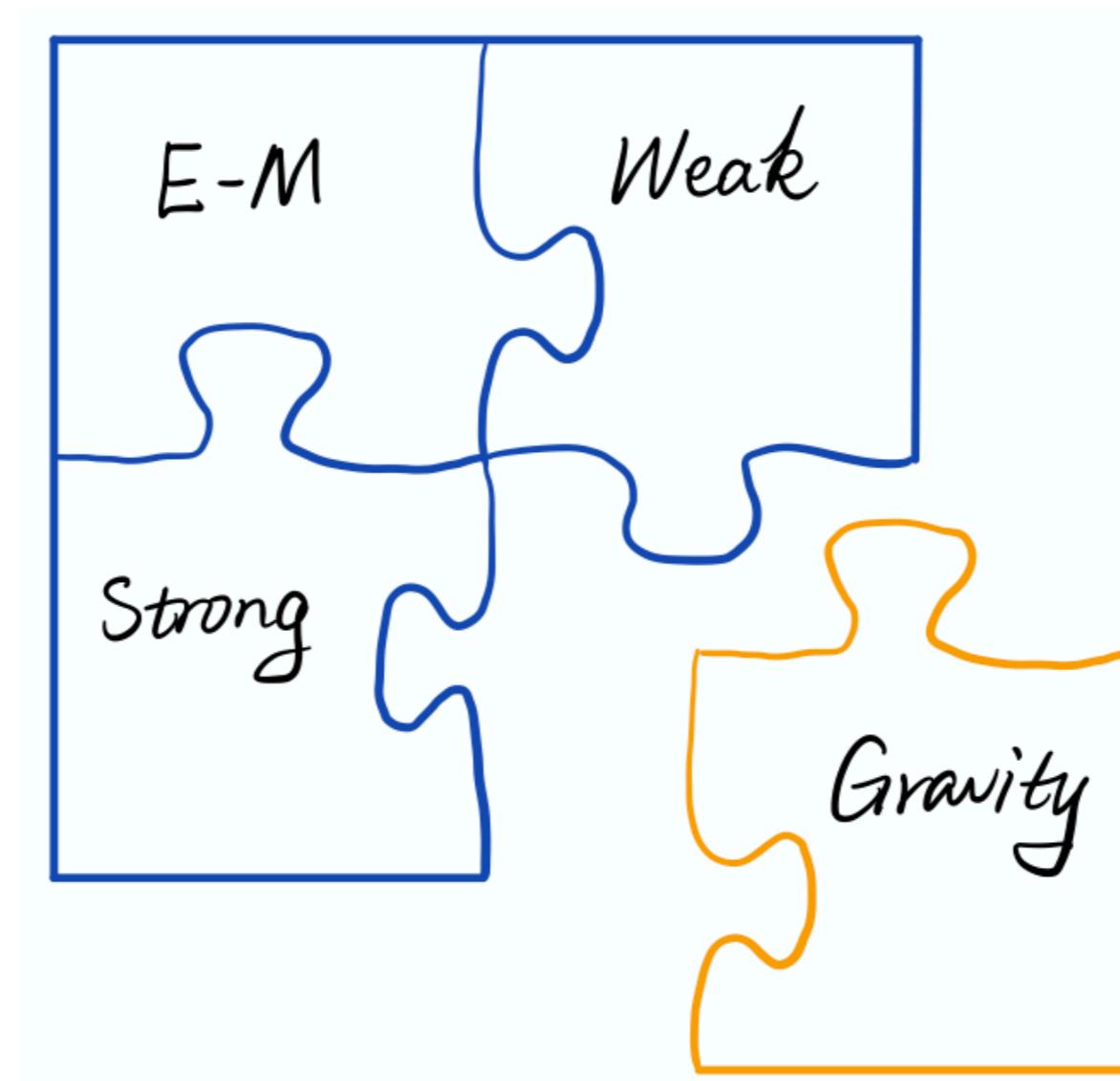
Based on: Zeyu Li and GY, arXiv:2312.04319; Zeyu Li, GY, Guorui Zhu in preparation

ShanghaiTech University, Shanghai, China, July 1-5

Outline

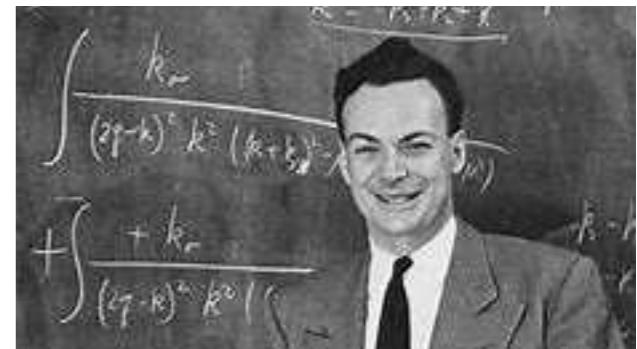
- Introduction
- Constructing CK-dual numerators
- New strategy of deformation
- Summary and outlook

Gauge and gravity theories



What is “quantum gravity”?

Feynman and quantum gravity



QUANTUM THEORY OF GRAVITATION*

By R. P. FEYNMAN

(Received July 3, 1963)

My subject is the quantum theory of gravitation. My interest in it is primarily in the relation of one part of nature to another. There's a certain irrationality to any work in gravitation, so it's hard to explain why you do any of it; for example, as far as quantum effects are concerned let us consider the effect of the gravitational attraction between an electron and a proton in a hydrogen atom; it changes the energy a little bit. Changing the energy of a quantum system means that the phase of the wave function is slowly shifted relative to what it would have been were no perturbation present. The effect of gravitation on the hydrogen atom is to shift the phase by 43 seconds of phase in every hundred times the lifetime of the universe! An atom made purely by gravitation, let us say two neutrons held together by gravitation, has a Bohr orbit of 10^8 light years. The energy of this system is 10^{-70} rydbergs. I wish to discuss here the possibility of calculating the Lamb correction to this thing, an energy, of the order 10^{-120} . This irrationality is shown also in the strange gadgets of Prof. Weber, in the absurd creations of Prof. Wheeler and other such things, because the dimensions are so peculiar. It is therefore clear that the problem we are working on is not the correct problem; the correct problem is what determines the size of gravitation? But since I am among equally irrational men I won't be criticized I hope for the fact that there is no possible, practical reason for making these calculations.

I am limiting myself to not discussing the questions of quantum geometry nor what happens when the fields are of very short wave length. I am not trying to discuss any problems which we don't already have in present quantum field theory of other fields, not that I believe that gravitation is incapable of solving the problems that we have in the present theory, but because I wish to limit my subject. I suppose that no wave lengths are shorter than one-millionth of the Compton wave length of a proton, and therefore it is legitimate to analyze everything in perturbation approximation; and I will carry out the perturbation approximation as far as I can in every direction, so that we can have as many terms as we want, which means that we can go to ten to the minus two-hundred and something rydbergs.

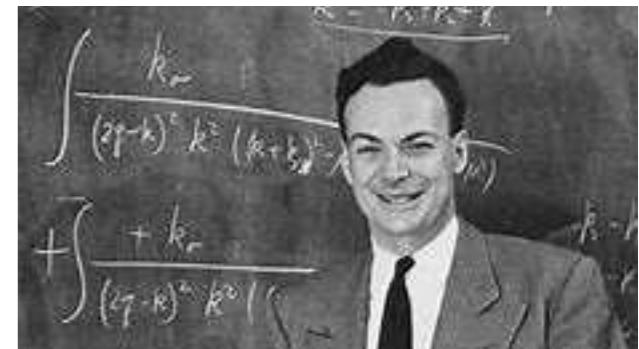
I am investigating this subject despite the real difficulty that there are no experiments. Therefore there is so real challenge to compute true, physical situations. And so I made

“There's a certain **irrationality** to any work in gravitation.”

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Feynman and quantum gravity



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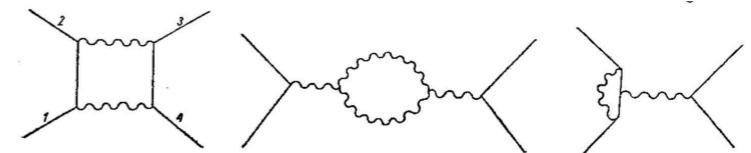


Fig. 5

By studying loop diagrams, Feynman made discoveries that are important for gauge theory:

- Feynman's tree theorem
- The idea of Faddeev-Popov quantization and ghost

Higher loop gravity

High-loop gravity can be very difficult using Feynman diagram:

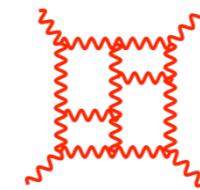
3-vertex
more than
100 terms

3-loop



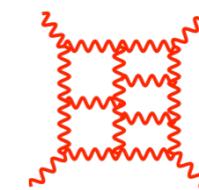
$\sim 10^{20}$ terms

4-loop

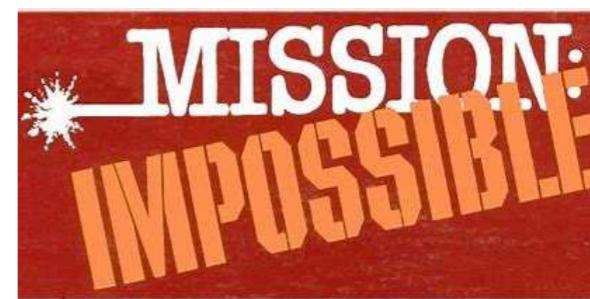


$\sim 10^{26}$ term

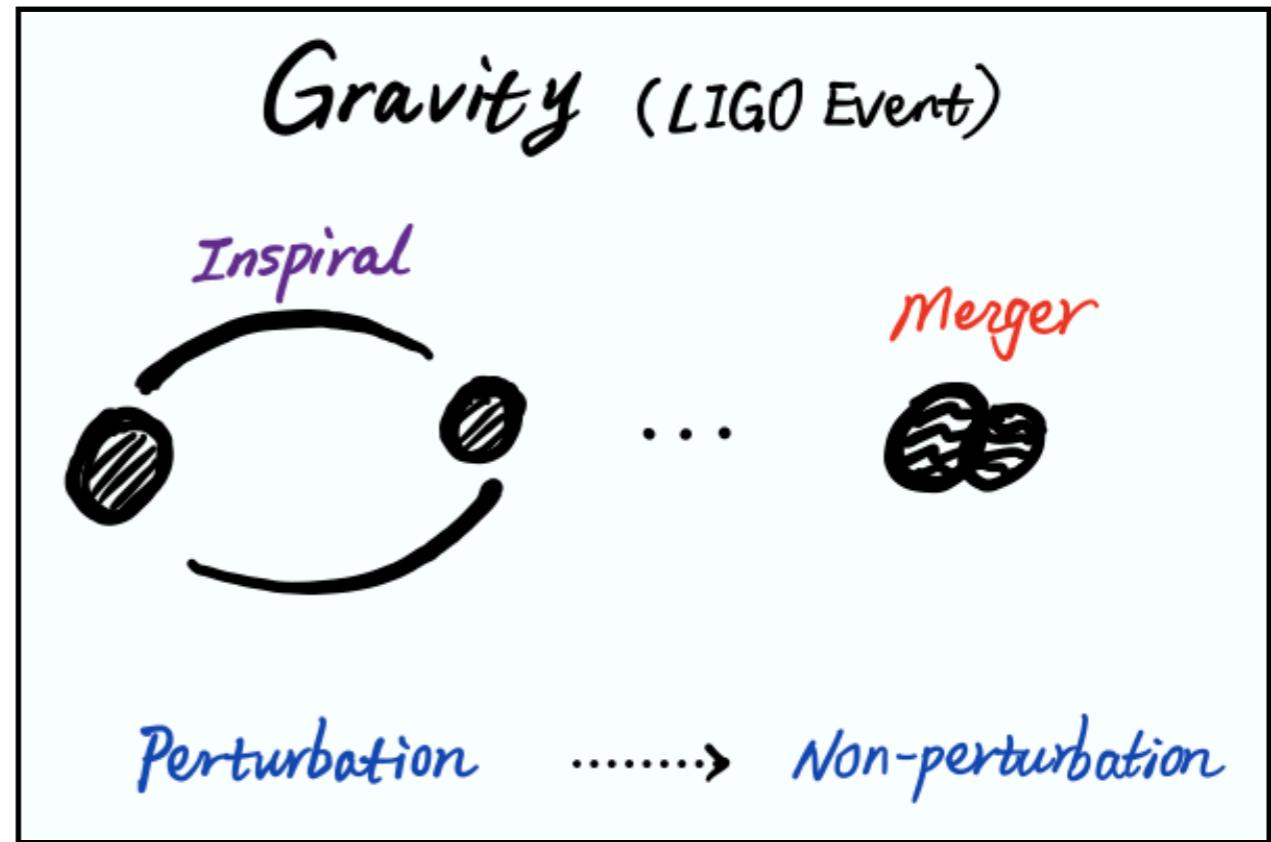
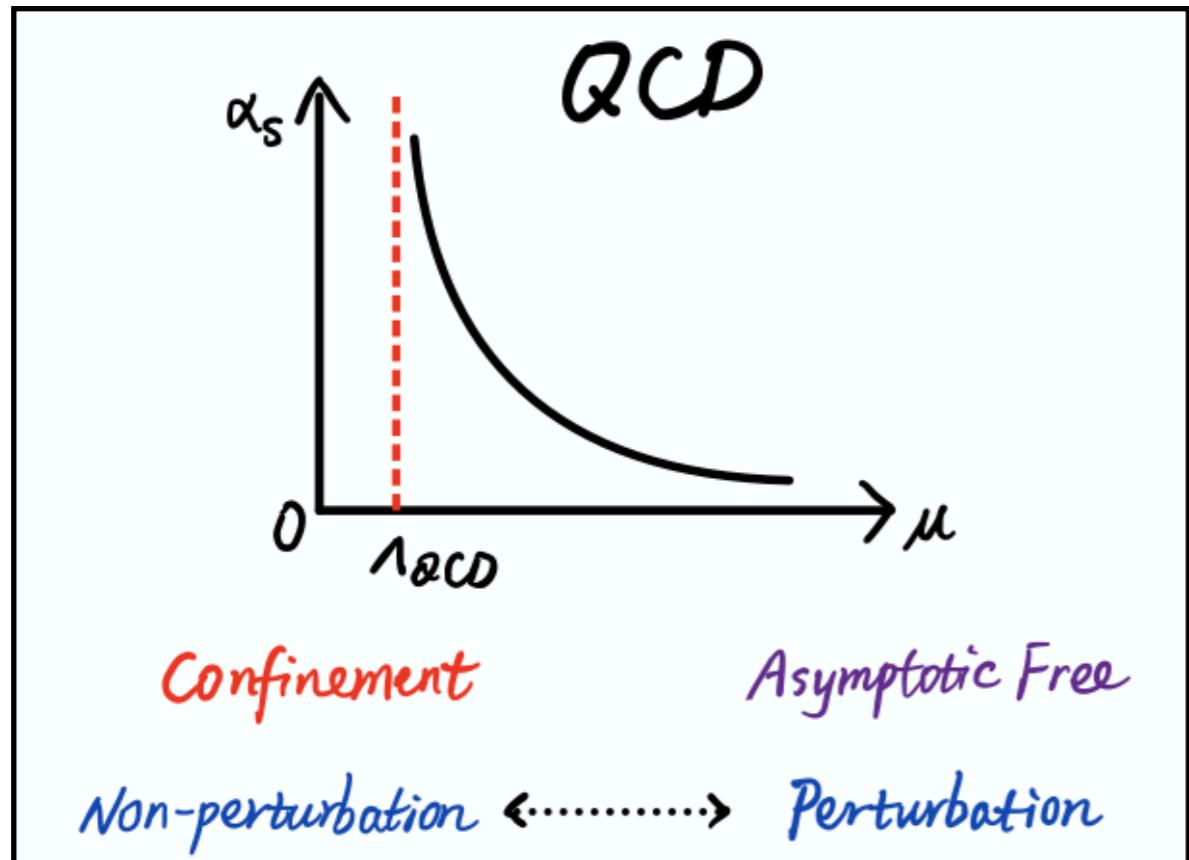
5-loop



$\sim 10^{31}$ terms

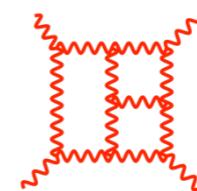


Higher loop perturbation is important

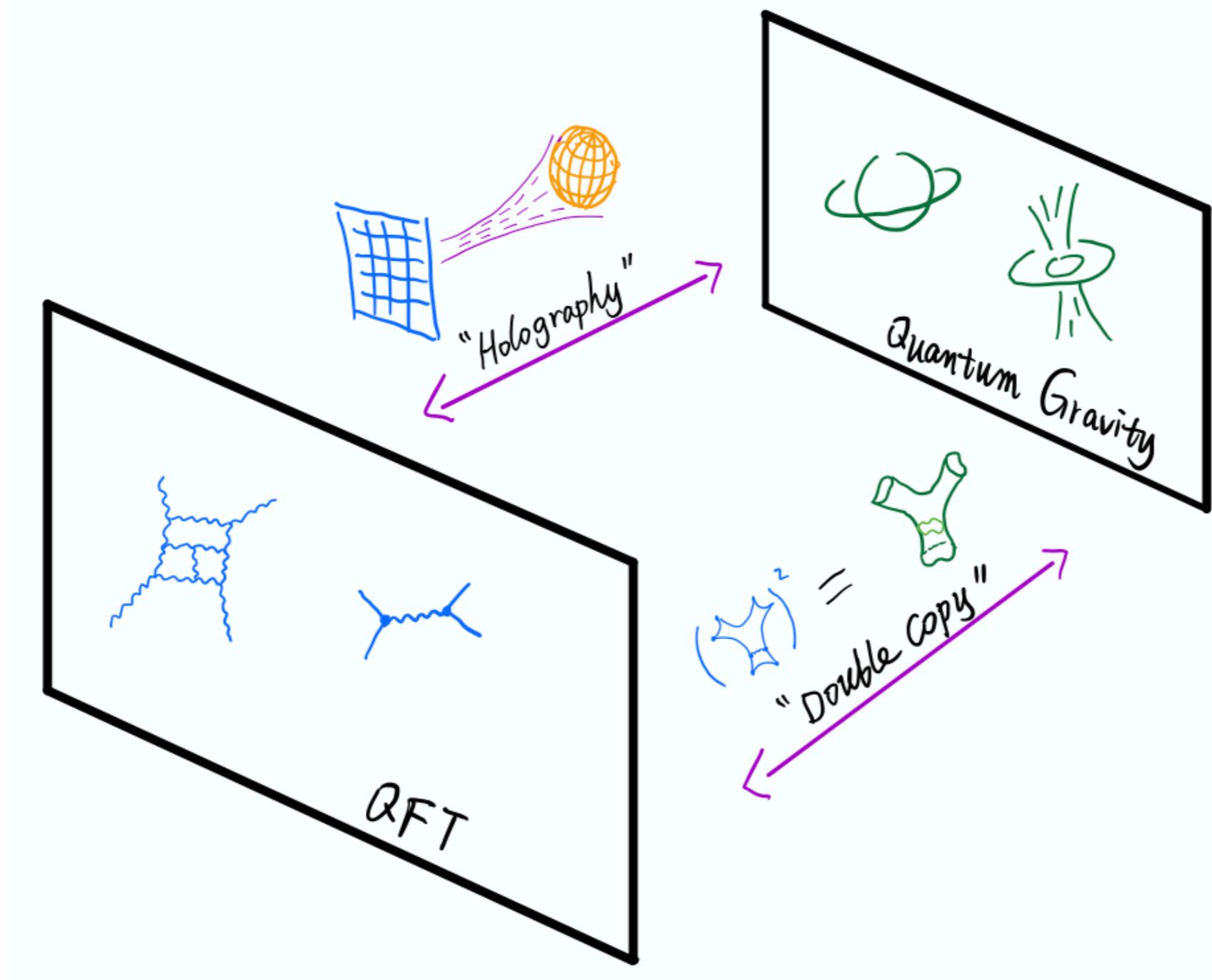


Understanding the structure of ultraviolet divergences in gravity:

$$\mathcal{L} = \sqrt{-g}(R + c_1 R^2 + c_2 R_{\mu\nu} R^{\mu\nu} + c_3 R_{\mu\nu\rho\sigma} R^{\mu\nu\rho\sigma} + \dots)$$

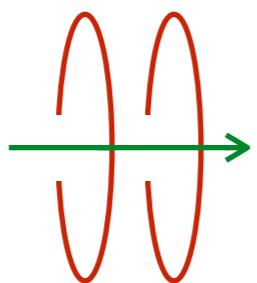


From gauge theory to gravity

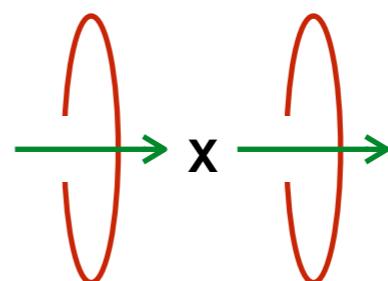


Double copy

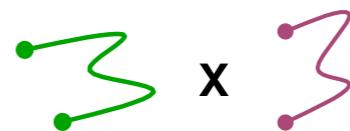
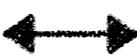
$$\text{Gravity} \simeq (\text{Yang-Mills})^2$$



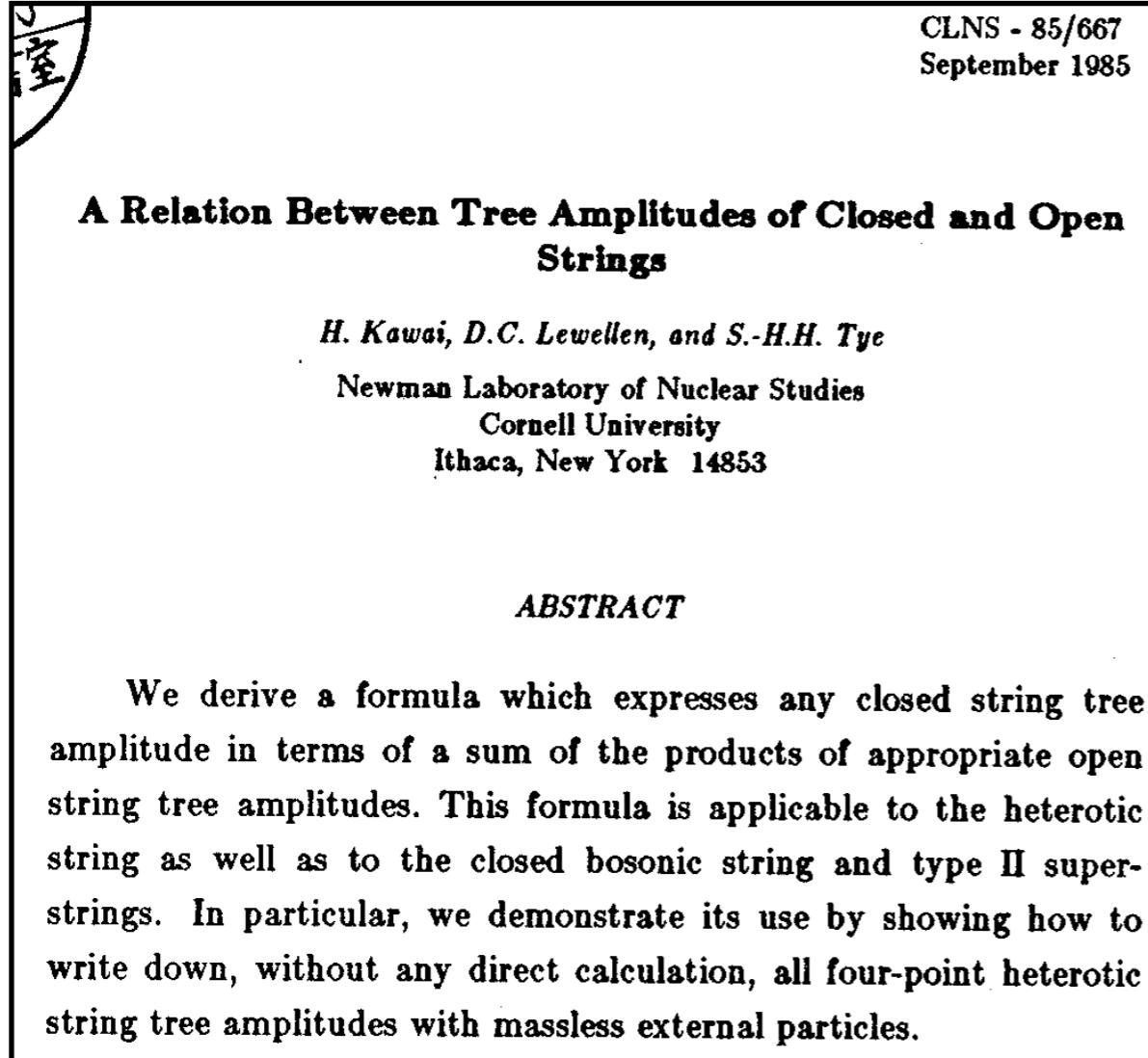
Spin-2



(spin-1) $\wedge 2$



Double copy



KLT relation:



$$A_{closed}^{(4)} = -\pi \kappa^2 \sin(\pi \kappa_1 \cdot \kappa_2) A_{open}^{(4)}(s, t) \bar{A}_{open}^{(4)}(s, u)$$

$$\begin{aligned} A_{closed}^{(5)} = & \pi \kappa^3 A_{open}^{(5)}(12345) \bar{A}_{open}^{(5)}(21435) \sin(\pi \kappa_1 \cdot \kappa_2) \sin(\pi \kappa_3 \cdot \kappa_4) \\ & + \pi \kappa^3 A_{open}^{(5)}(13245) \bar{A}_{open}^{(5)}(31425) \sin(\pi \kappa_1 \cdot \kappa_3) \sin(\pi \kappa_2 \cdot \kappa_4). \end{aligned}$$



Field theory limit

$$M_4^{\text{tree}}(1, 2, 3, 4) = -is_{12} A_4^{\text{tree}}(1, 2, 3, 4) A_4^{\text{tree}}(1, 2, 4, 3),$$

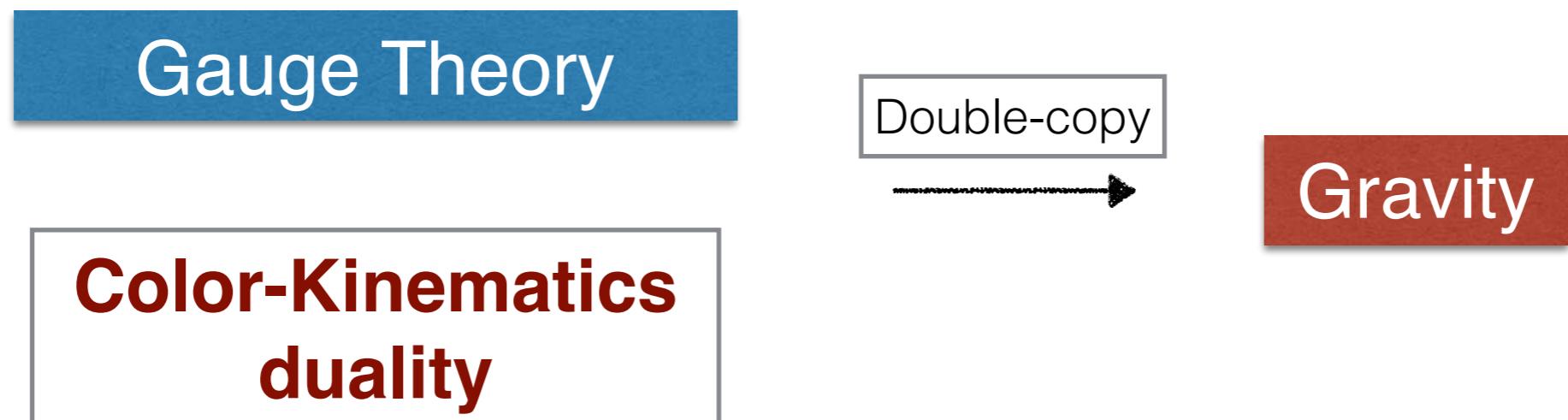
$$\begin{aligned} M_5^{\text{tree}}(1, 2, 3, 4, 5) = & is_{12}s_{34} A_5^{\text{tree}}(1, 2, 3, 4, 5) A_5^{\text{tree}}(2, 1, 4, 3, 5) \\ & + is_{13}s_{24} A_5^{\text{tree}}(1, 3, 2, 4, 5) A_5^{\text{tree}}(3, 1, 4, 2, 5) \end{aligned}$$

New ideas are needed for loop level.

Color-kinematics duality

The idea of color-kinematics duality was introduced by Bern, Carrasco, and Johansson in 2008.

Bern, Carrasco, Johansson 2008



Generalizing double-copy to quantum (loop) level.

Color-kinematics duality

$$A_n = i g^{n-2} \sum_{(\text{cubic graph})_i} \frac{C_i \ n_i}{\pi D_{\alpha_i}} \xrightarrow{\substack{C_i \text{ red arrow} \\ \text{Kinematic factor}}} \text{Kinematic factor}$$

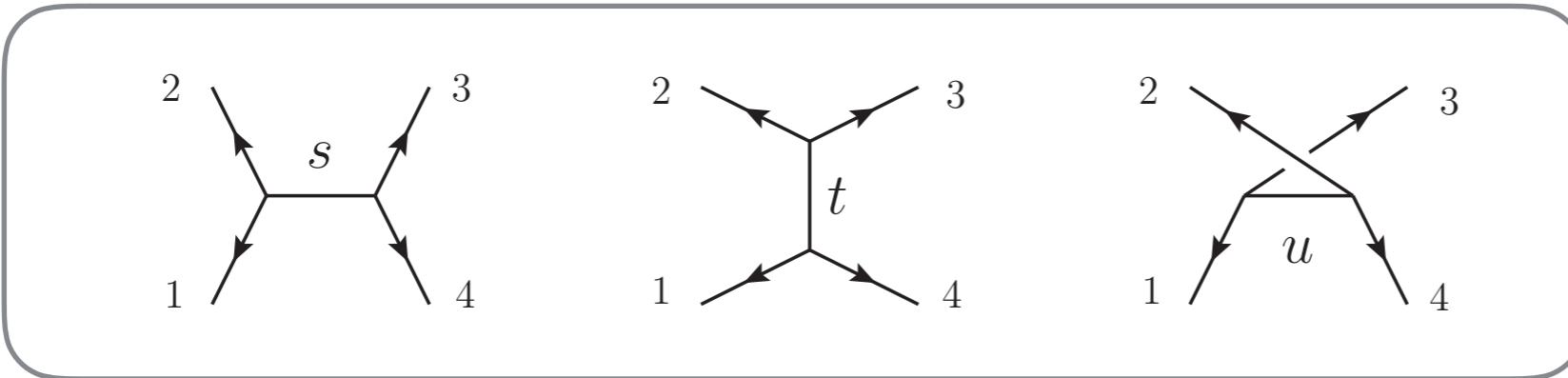
$\xrightarrow{\substack{n_i \text{ blue arrow} \\ \text{Propagator}}}$



$$C_i + C_j + C_k = 0 \Rightarrow n_i + n_j + n_k = 0$$

$$M_n = i K^{n-2} \sum_{(\text{cubic graph})_i} \frac{n_i \ n_i}{\pi D_{\alpha_i}}$$

Example: 4-pt amplitude



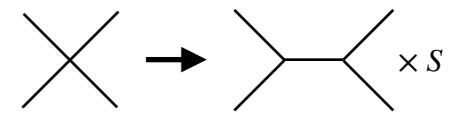
$$A_4(1,2,3,4) = \frac{c_s n_s}{s} + \frac{c_t n_t}{t} + \frac{c_u n_u}{u}$$

$$c_s = \tilde{f}^{a_1 a_2 b} \tilde{f}^{b a_3 a_4}, \quad c_t = \tilde{f}^{a_2 a_3 b} \tilde{f}^{b a_4 a_1}, \quad c_u = \tilde{f}^{a_1 a_3 b} \tilde{f}^{b a_2 a_4}$$

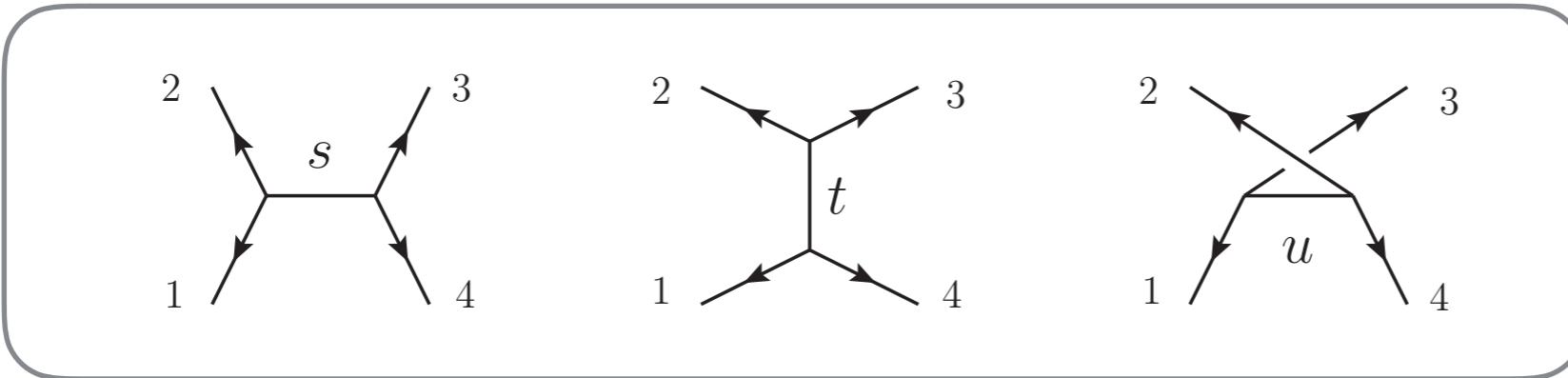
$$c_s = c_t + c_u \quad \Rightarrow \quad n_s = n_t + n_u$$

Jacobi identity

dual Jacobi relation



Example: 4-pt amplitude



$$A_4(1,2,3,4) = \frac{c_s n_s}{s} + \frac{c_t n_t}{t} + \frac{c_u n_u}{u}$$

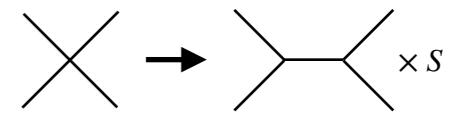
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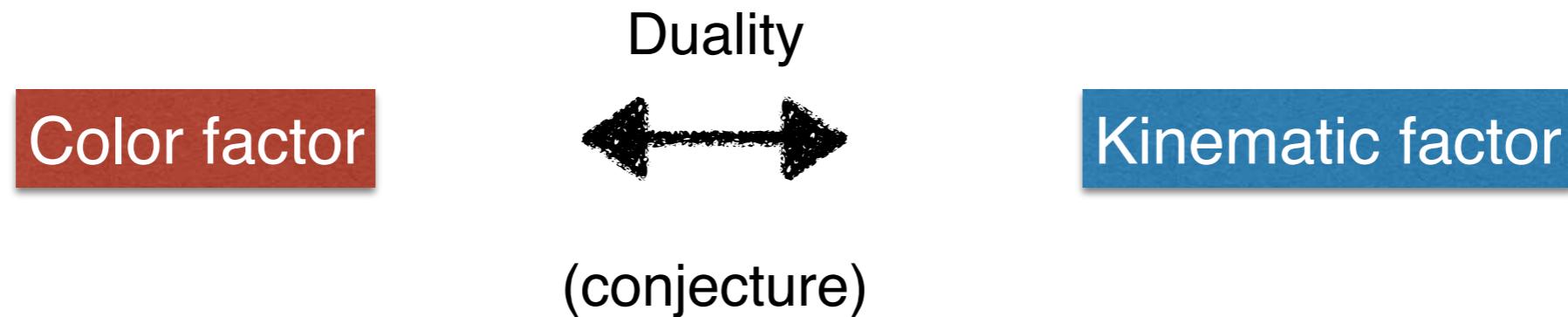
dual Jacobi relation

$$M_4(1,2,3,4) = \frac{n_s n_s}{s} + \frac{n_t n_t}{t} + \frac{n_u n_u}{u}$$



Color-kinematics duality

$$A_n = i g^{n-2} \sum_{(\text{cubic graph})_i} \frac{C_i \ n_i}{\pi D_{\alpha_i}} \begin{array}{l} \xrightarrow{\text{Color factor}} \\ \xrightarrow{\text{Kinematic factor}} \\ \xrightarrow{\text{Propagator}} \end{array}$$



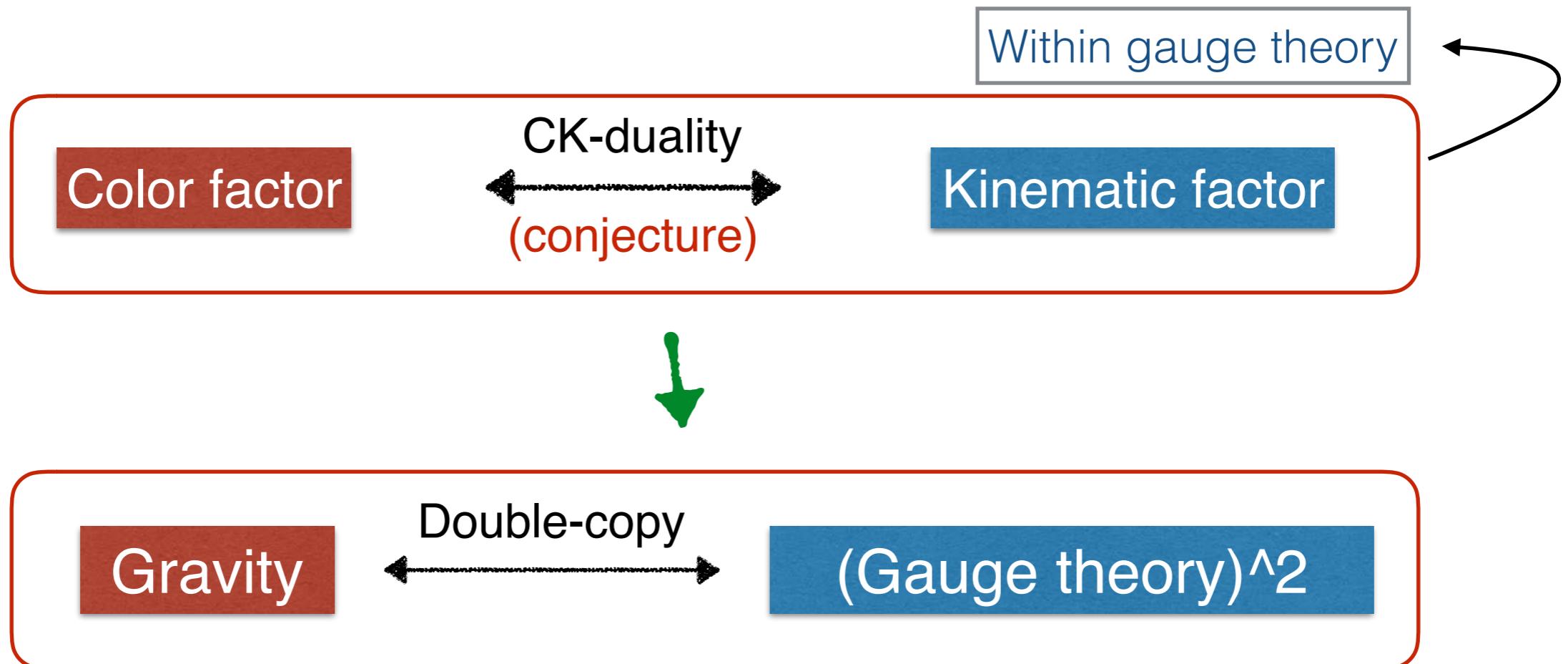
$$\tilde{f}^{abc} = \text{Tr}([T^a, T^b]T^c)$$

$$s_{ij} = (p_i + p_j)^2$$

Gauge symmetry

Spacetime symmetry

CK-duality v.s. Double-copy



By studying the simpler gauge theory, one may understand the far more complicated gravity theory.

Outline

- Introduction
- **Constructing CK-dual numerators**
- New strategy of deformation
- Summary and outlook

Constructing CK-dual integrand

CK-duality

$$c_s = c_t + c_u \Rightarrow n_s = n_t + n_u$$

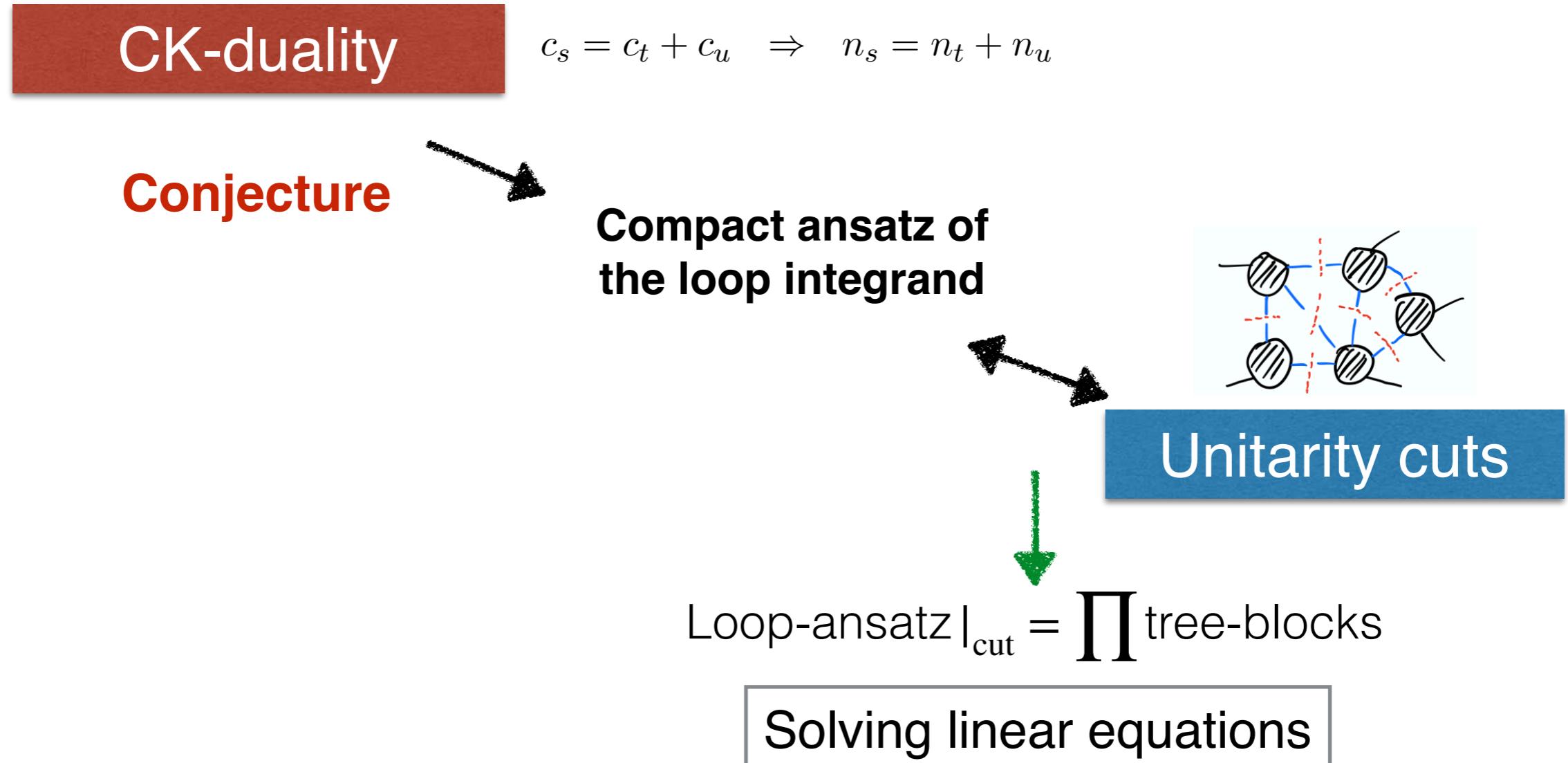
Conjecture



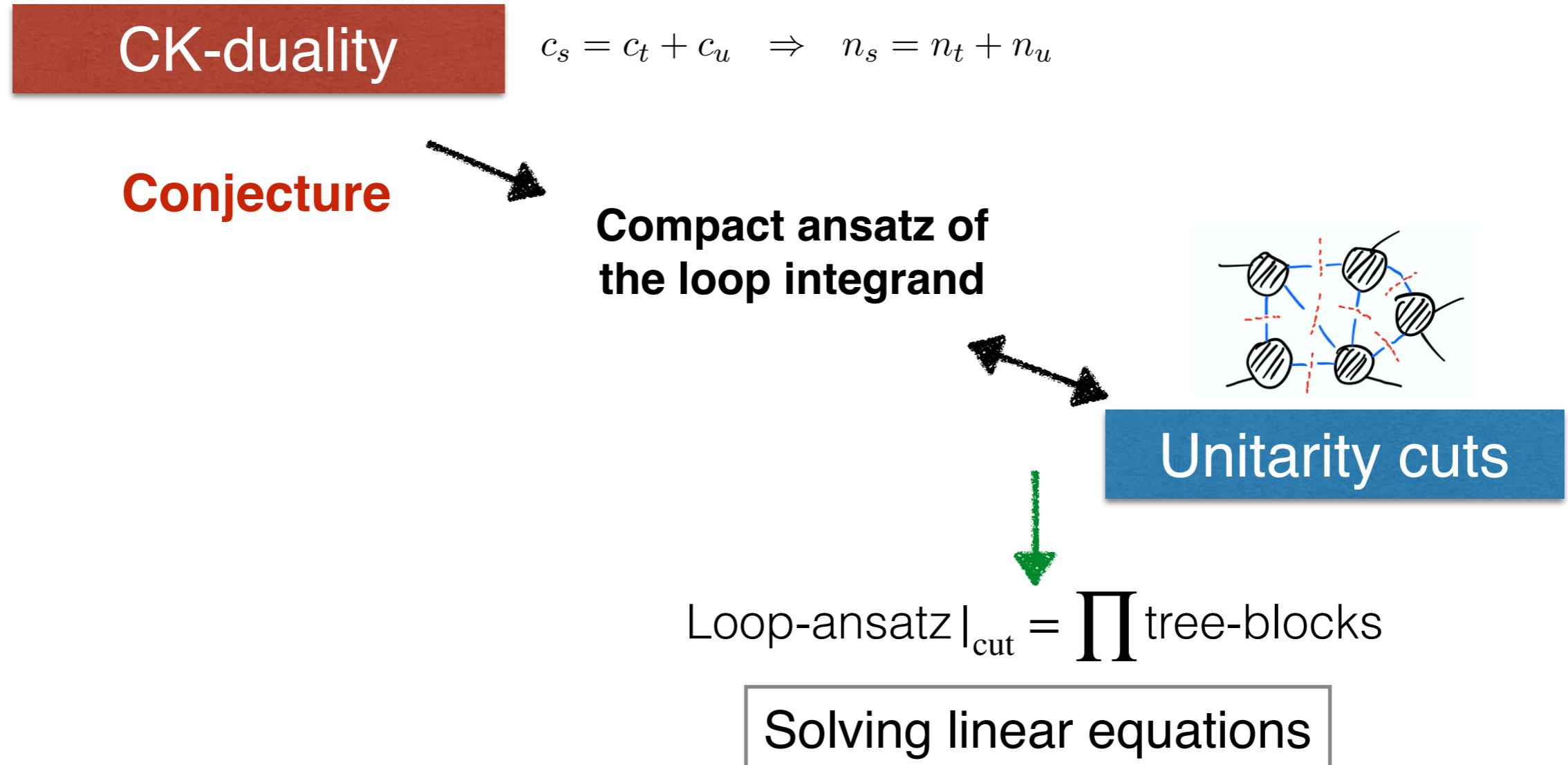
Compact ansatz of
the loop integrand

$$A^{(\ell)} \sim \sum_i \int \frac{C_i \times N_i}{\prod D}$$

Constructing CK-dual integrand



Constructing CK-dual integrand



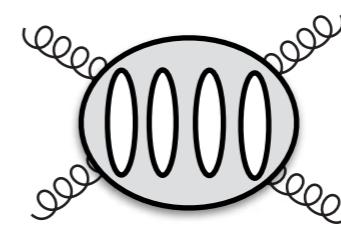
Main challenge: it is a priori not known whether the solution exists

Loop-level CK duality

For $N=4$ SYM, there are high loop examples that manifest
global CK-dual Jacobi relations:

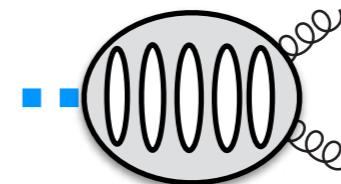
- 4-loop 4-point amplitude in $N=4$

Bern, Carrasco, Dixon, Johansson, Roiban, 2012



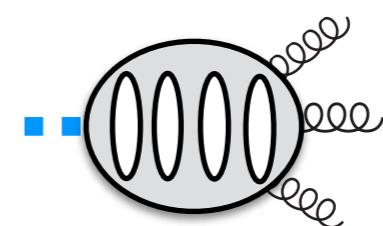
- 5-loop Sudakov form factor in $N=4$

GY, 2016

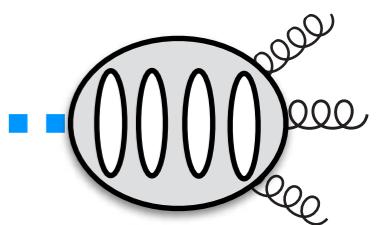


- 4-loop three-point form factor in $N=4$

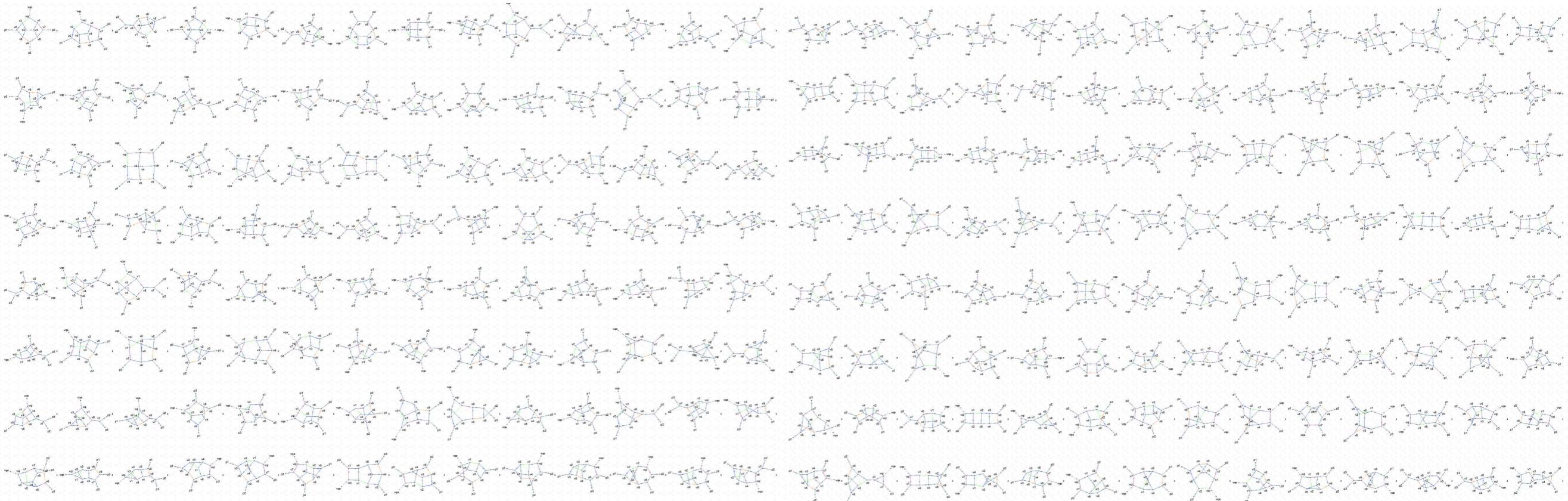
Lin, GY, Zhang, 2021



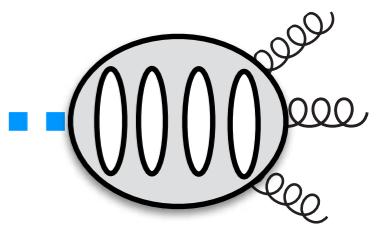
4-loop 3-point form factor



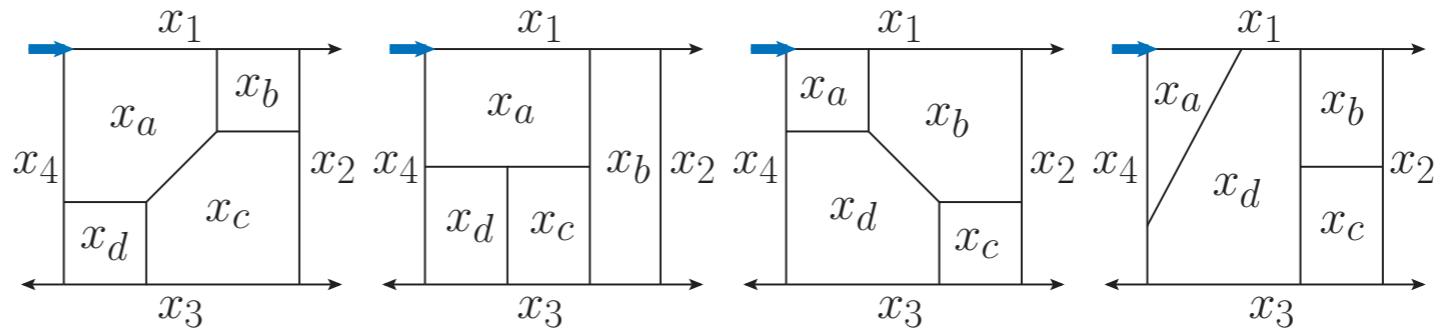
229 trivalent graphs



4-loop 3-point form factor



Master graphs



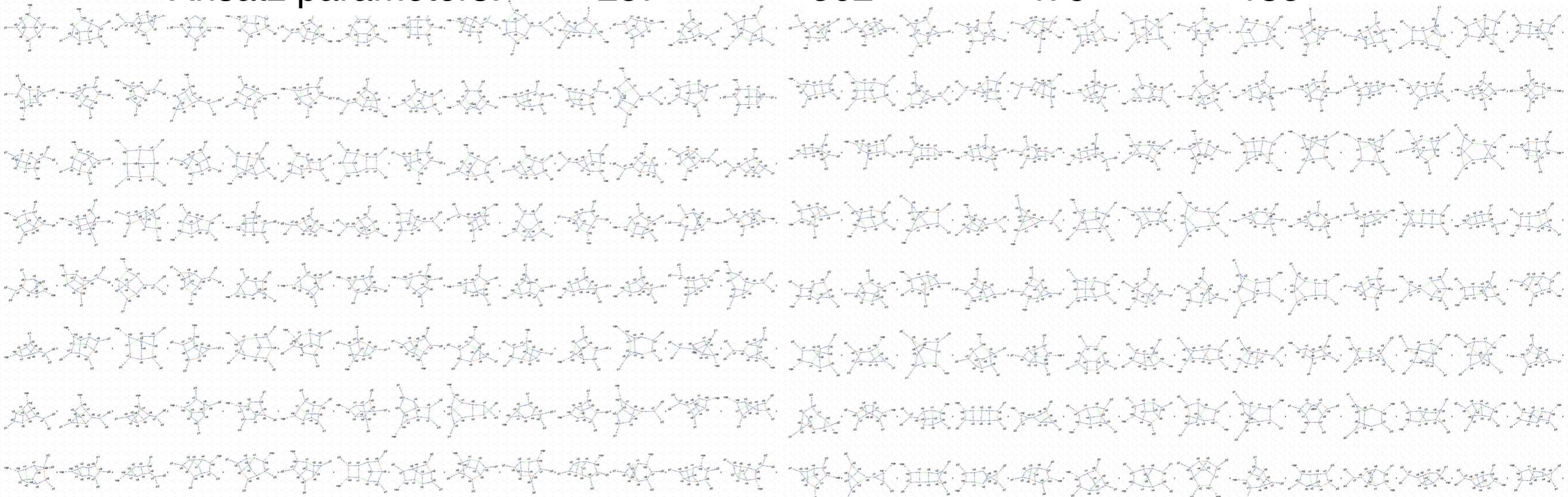
Ansatz parameters:

257

562

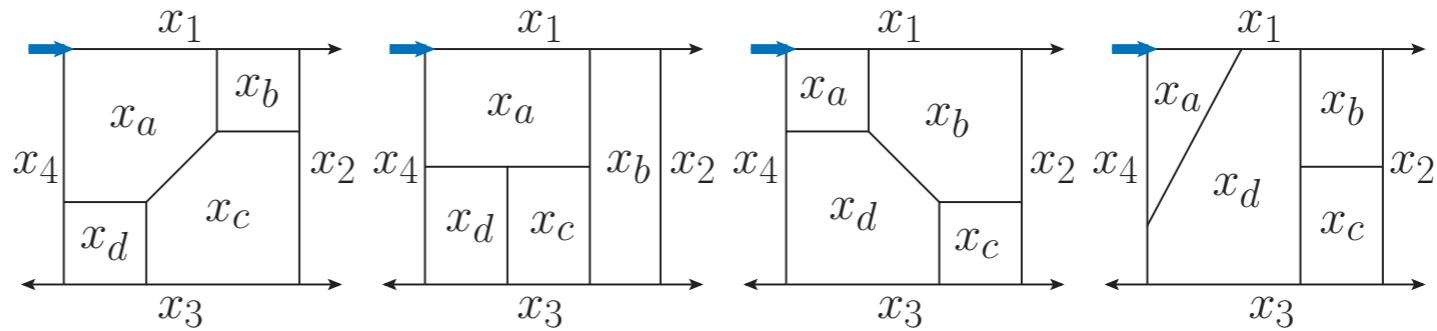
479

135

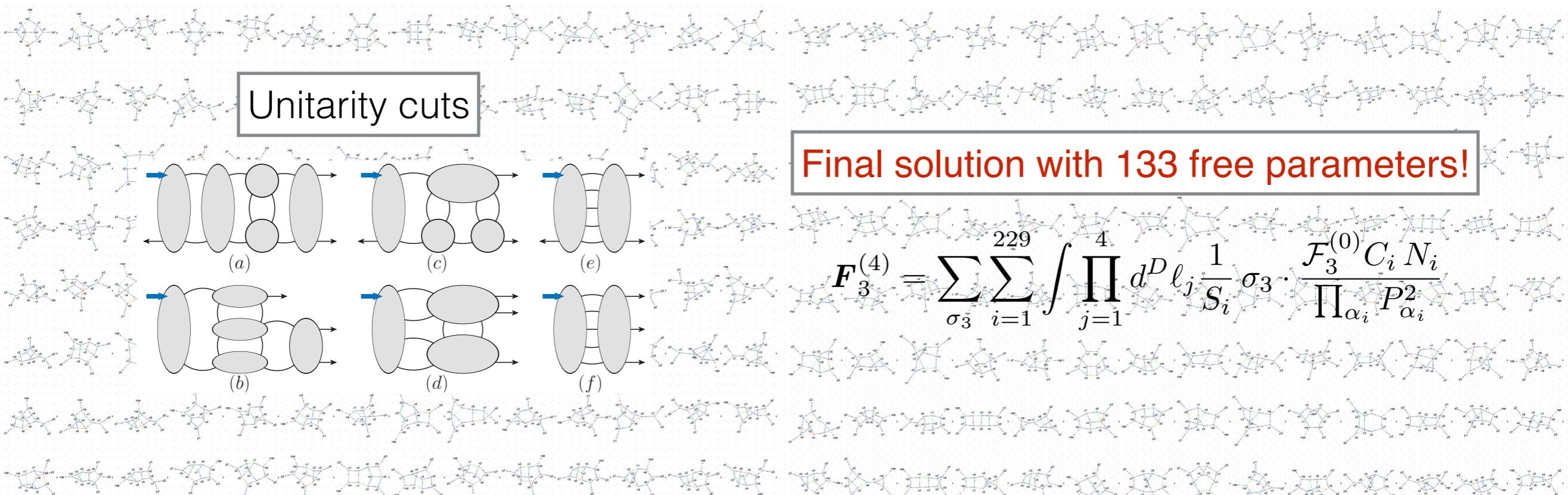


4-loop 3-point form factor

Master graphs

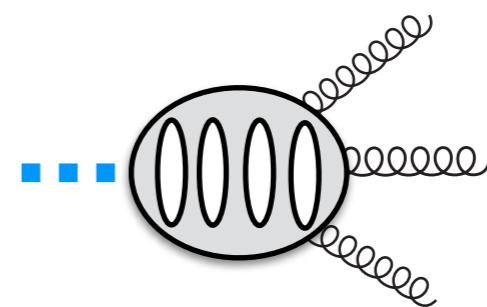


Unitarity cuts



Three-point form factor up to four loops

$$\mathcal{F}_3 = \int d^4x e^{-iq \cdot x} \langle p_1, p_2, p_3 | \text{tr}(F^2)(x) | 0 \rangle$$



L loops	$L=1$	$L=2$	$L=3$	$L=4$
# of cubic graphs	2	6	29	229
# of planar masters	1	2	2	4
# of free parameters	1	4	24	133

Non-supersymmetric Yang-Mills

For non-supersymmetric YM, even two-loop is challenging:

- 2-loop 4-gluon all-plus-helicity amplitude in pure YM

$$A_4^{(2)}(1^+, 2^+, 3^+, 4^+)$$

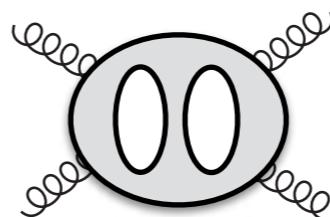
Bern, Davies, Dennen, Huang, Nohle 2013

- 2-loop 5-gluon all-plus-helicity amplitude in pure YM

$$A_5^{(2)}(1^+, 2^+, 3^+, 4^+, 5^+)$$

O'Connell and Mogull 2015

No global CK-dual solution is known for generic helicity configurations at two loops.



When difficult to find CK-dual solution

- Enlarge ansatz (e.g. increasing power of loop momenta)

$$A_5^{(2)}(1^+, 2^+, 3^+, 4^+, 5^+)$$

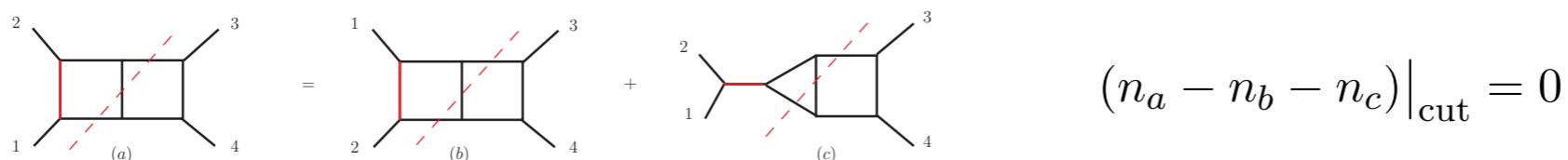
$$n^{\text{CK}} \sim \ell^{12}$$

O'Connell and Mogull 2015

- Give up global CK relations?

Ansatz is made to all topologies and only imposing CK-duality on cuts.

Bern, Davies and Nohle 2015



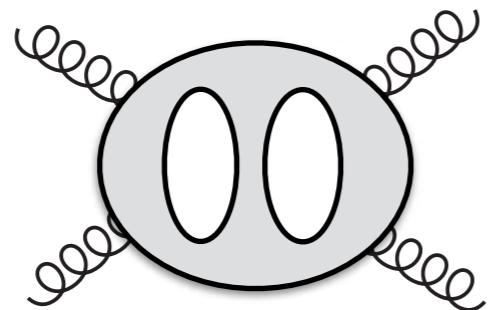
Hard to generalize to higher-loop/point cases.

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Two-loop 4-gluon amplitude

We introduce a strategy by allowing “**deformation**”.

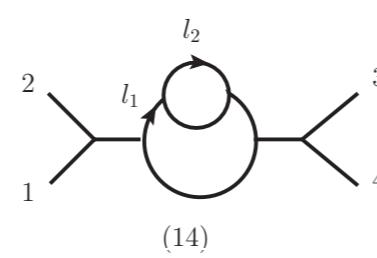
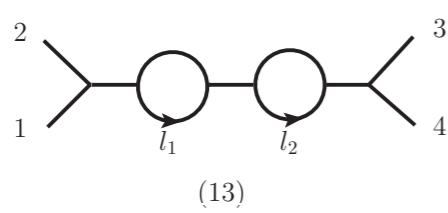
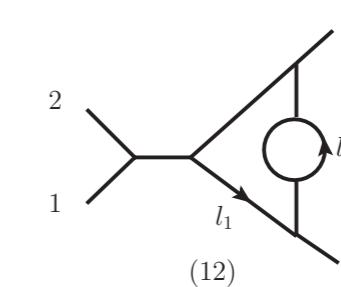
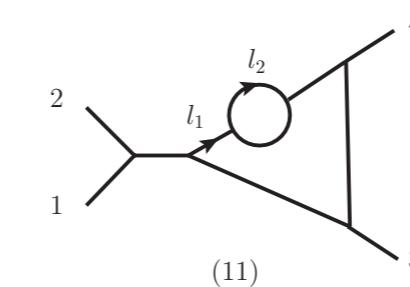
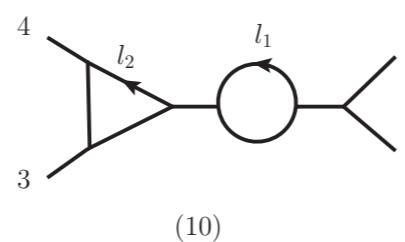
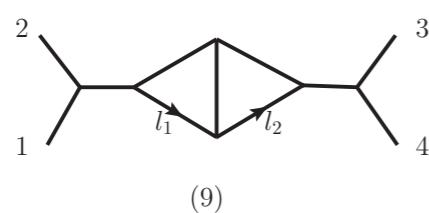
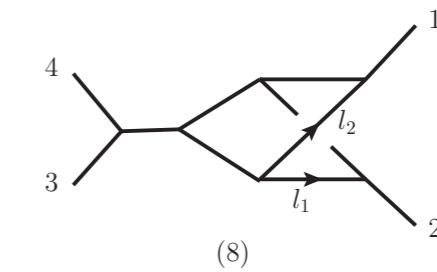
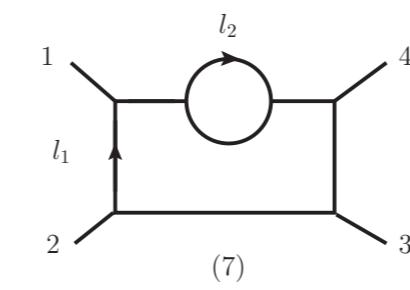
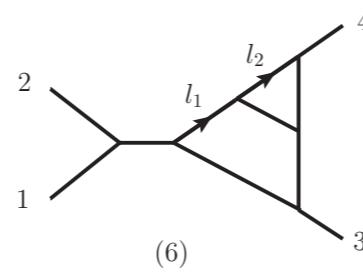
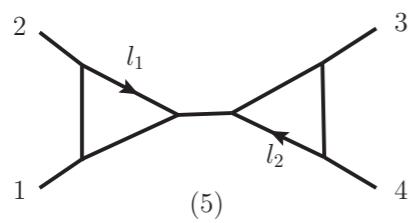
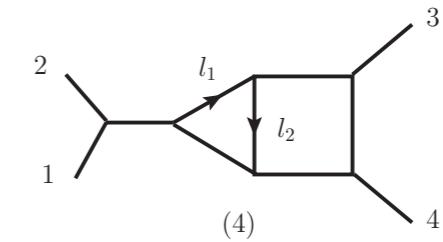
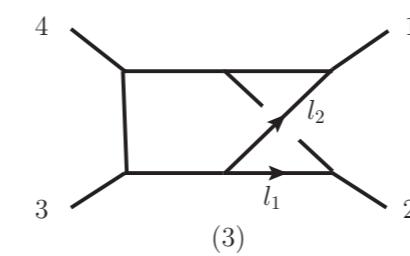
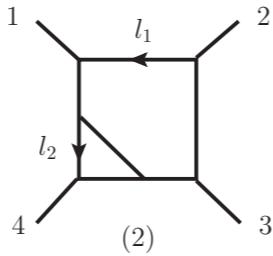
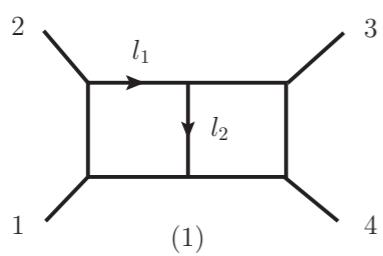


$$N_1 = n_1 + \Delta_1$$

Let us first review the standard construction.

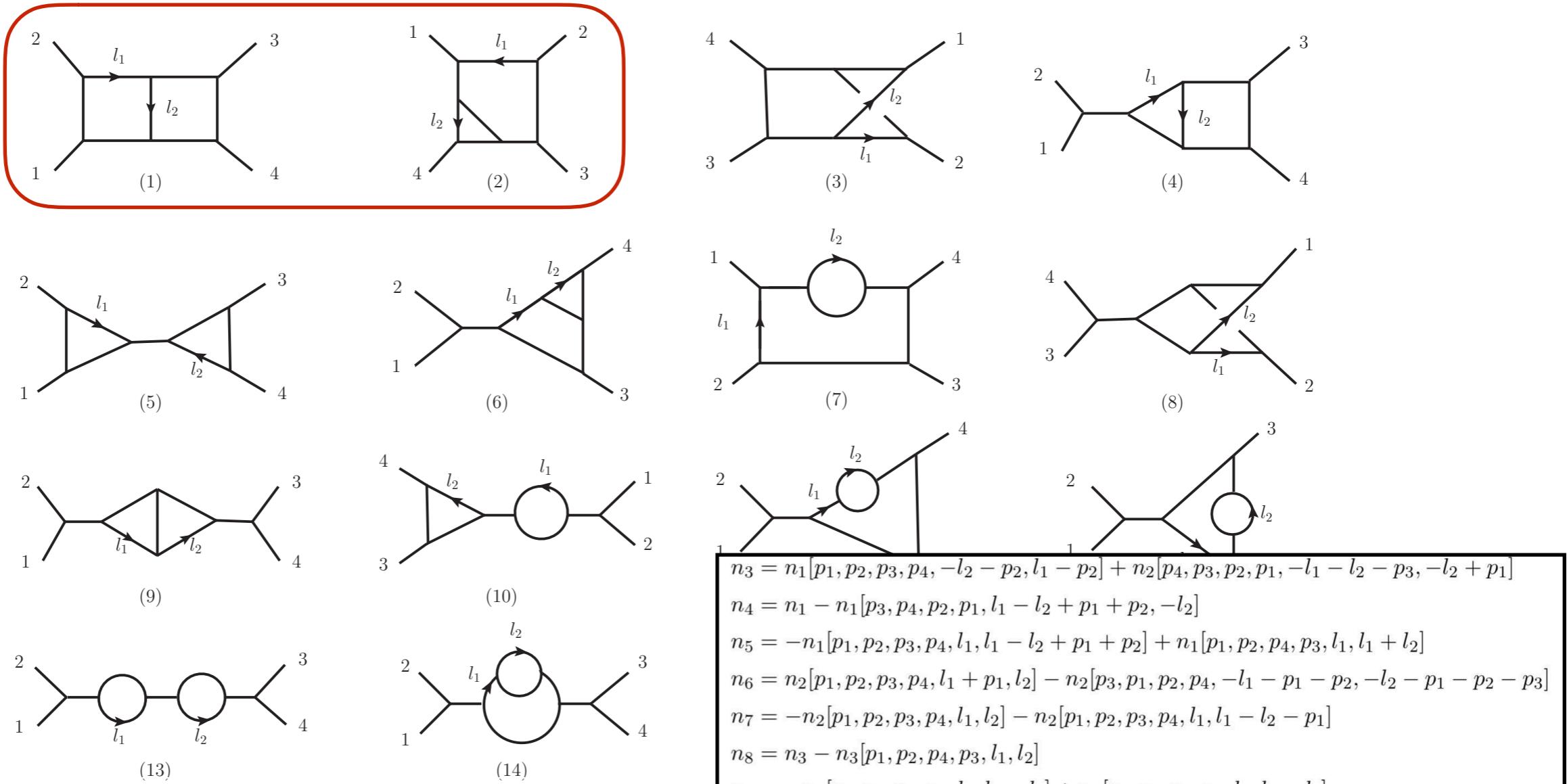
$$N_1 = \boxed{n_1} + \Delta_1$$

Two-loop trivalent diagrams



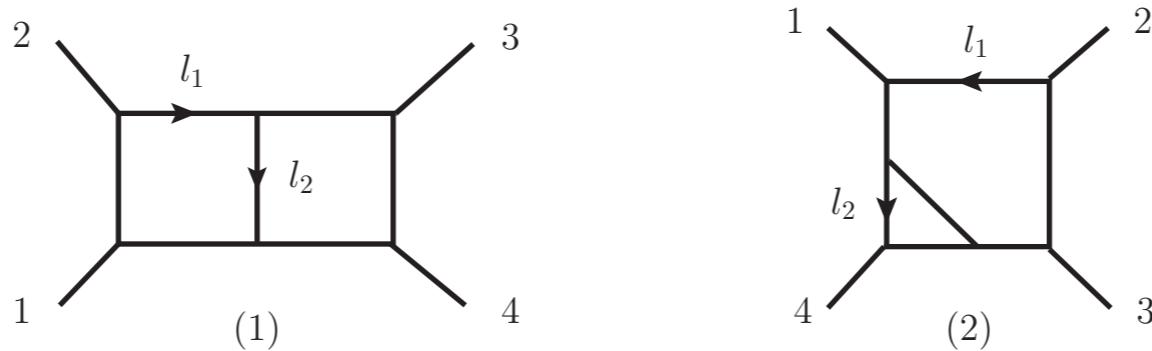
Two-loop trivalent diagrams

Master topologies



$$\begin{aligned}
 n_3 &= n_1[p_1, p_2, p_3, p_4, -l_2 - p_2, l_1 - p_2] + n_2[p_4, p_3, p_2, p_1, -l_1 - l_2 - p_3, -l_2 + p_1] \\
 n_4 &= n_1 - n_1[p_3, p_4, p_2, p_1, l_1 - l_2 + p_1 + p_2, -l_2] \\
 n_5 &= -n_1[p_1, p_2, p_3, p_4, l_1, l_1 - l_2 + p_1 + p_2] + n_1[p_1, p_2, p_4, p_3, l_1, l_1 + l_2] \\
 n_6 &= n_2[p_1, p_2, p_3, p_4, l_1 + p_1, l_2] - n_2[p_3, p_1, p_2, p_4, -l_1 - p_1 - p_2, -l_2 - p_1 - p_2 - p_3] \\
 n_7 &= -n_2[p_1, p_2, p_3, p_4, l_1, l_2] - n_2[p_1, p_2, p_3, p_4, l_1, l_1 - l_2 - p_1] \\
 n_8 &= n_3 - n_3[p_1, p_2, p_4, p_3, l_1, l_2] \\
 n_9 &= -n_4[p_1, p_2, p_3, p_4, l_1, l_1 - l_2] + n_4[p_1, p_2, p_4, p_3, l_1, l_1 - l_2] \\
 n_{10} &= -n_4[p_1, p_2, p_3, p_4, l_1, l_1 + l_2 + p_1 + p_2] - n_4[p_1, p_2, p_3, p_4, -l_1 - p_1 - p_2, -l_1 + l_2] \\
 n_{11} &= -n_4[p_1, p_2, p_3, p_4, -l_2 - p_1 - p_2, l_1 - l_2] - n_4[p_1, p_2, p_3, p_4, -l_1 + l_2 - p_1 - p_2, l_2] \\
 n_{12} &= -n_6[p_1, p_2, p_3, p_4, l_1, l_1 - l_2] - n_6[p_1, p_2, p_3, p_4, l_1, l_2 - p_1 - p_2 - p_3] \\
 n_{13} &= n_9 + n_9[p_1, p_2, p_3, p_4, -l_1 - p_1 - p_2, l_2] \\
 n_{14} &= n_9[p_1, p_2, p_3, p_4, l_1 - l_2, l_1] + n_9[p_1, p_2, p_3, p_4, -l_2 - p_1 - p_2, -l_1 - p_1 - p_2],
 \end{aligned}$$

Ansatz for the master numerators



Polynomials in D-dim kinematics:

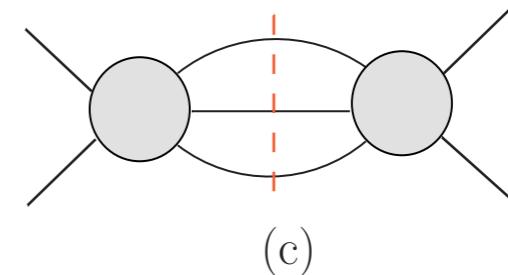
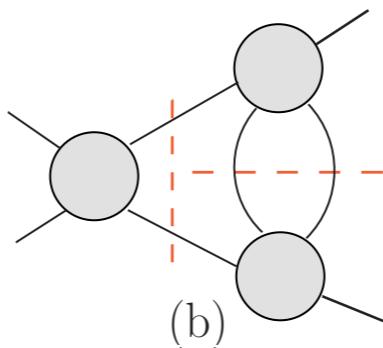
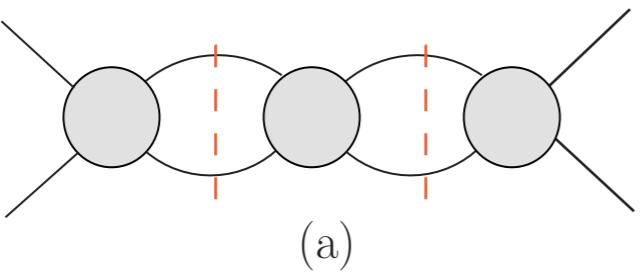
$$n_m = \sum_k a_{mk} M_k , \quad m = 1, 2 ,$$

$$\{\varepsilon_i \cdot \varepsilon_j, \varepsilon_i \cdot p_j, \varepsilon_i \cdot l_\alpha, p_i \cdot l_\alpha, l_\alpha \cdot l_\beta, p_1 \cdot p_2, p_2 \cdot p_3\}$$

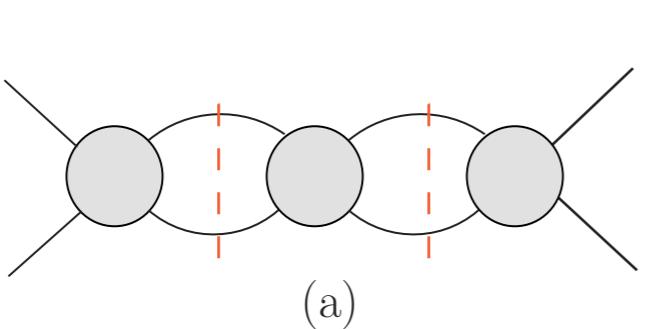
e.g.: $(\varepsilon_1 \cdot \varepsilon_2)(\varepsilon_3 \cdot \varepsilon_4)(p_1 \cdot p_2)(p_1 \cdot l_1)(p_1 \cdot l_2)$

Parameters: $\sim 20,000$ $\xrightarrow{\text{Symmetry}}$ ~ 1400

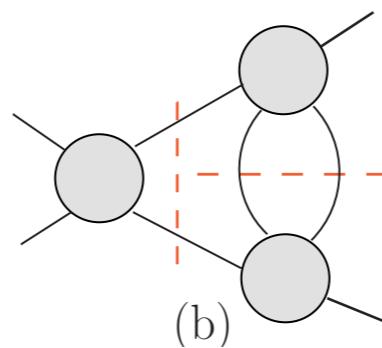
Unitarity cuts



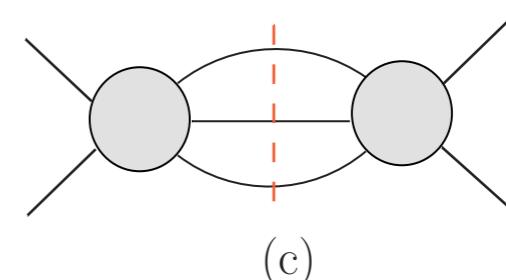
Unitarity cuts



(a)



(b)

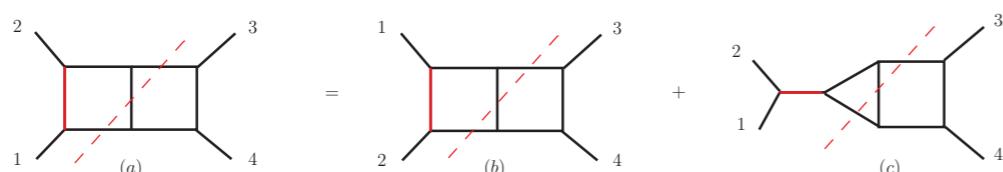


(c)



- Require the CK-duality at cut-level

Bern, Davies and Nohle 2015



$$(n_a - n_b - n_c)|_{\text{cut}} = 0$$

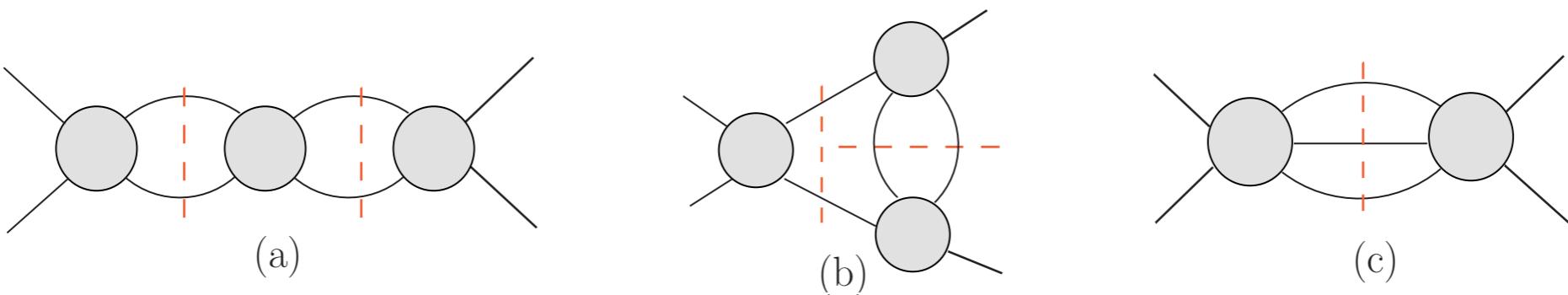
CK-duality only on cuts

initial parameters: $\sim 120,000$

after symmetry constraints: $\sim 28,000$

after cut and CK constraints: $\sim 6,300$

Unitarity cuts



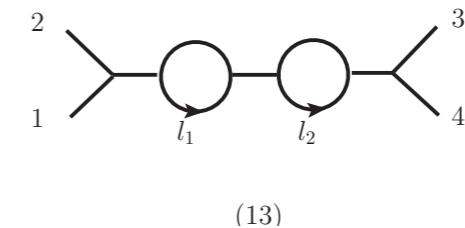
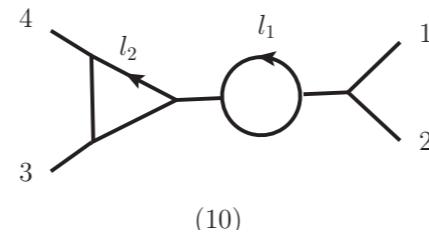
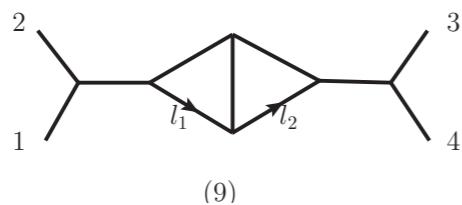
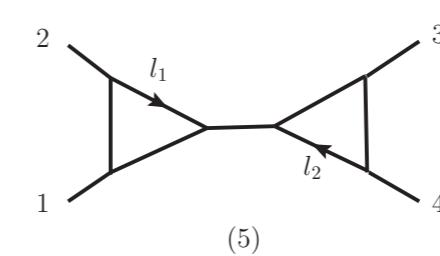
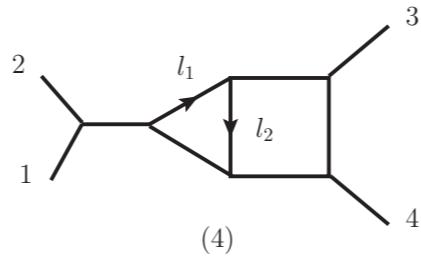
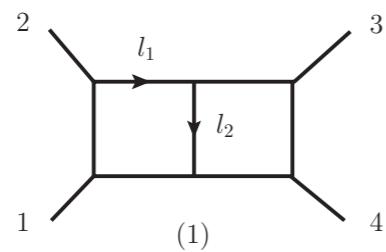
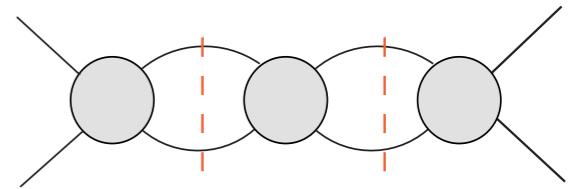
We would like to take advantage of the global CK-dual relations

$$N_i = n_i + \boxed{\Delta_i} \text{ Deformation} \rightarrow$$

A Feynman-like diagram consisting of three light-gray circular vertices connected by solid black horizontal lines. Two vertical dashed red lines, one between the first and second vertices, and another between the second and third, indicate a unitarity cut.

Deformed trivalent diagrams

Topologies that affect the ladder-double-cut:



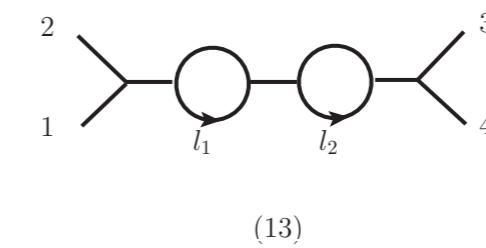
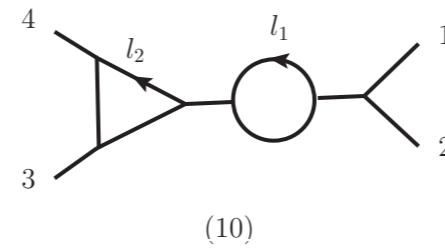
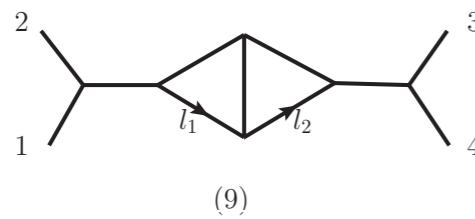
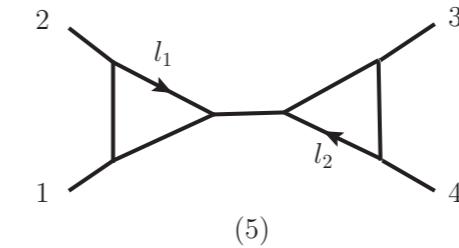
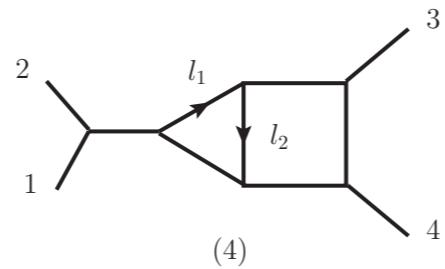
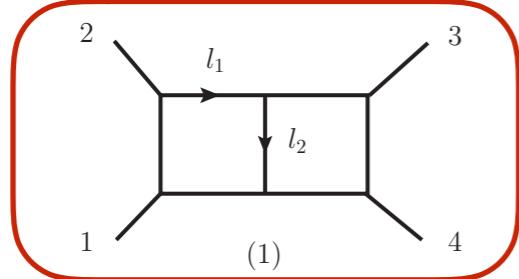
Deformation

$$N_i = \begin{cases} n_i + \Delta_i, & i = 1, 4, 5, 9, 10, 13, \\ n_i, & \text{others.} \end{cases}$$

Deformed numerators

We ask that deformation satisfies a sub-set of dual Jacobi relations.

Master topologies



$$\Delta_4 = \Delta_1 - \Delta_1[p_3, p_4, p_2, p_1, l_1 - l_2 + p_1 + p_2, -l_2]$$

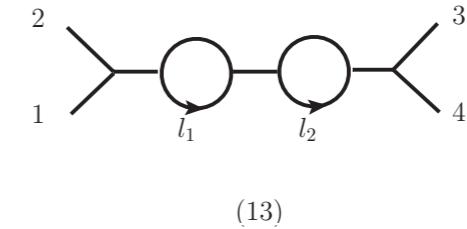
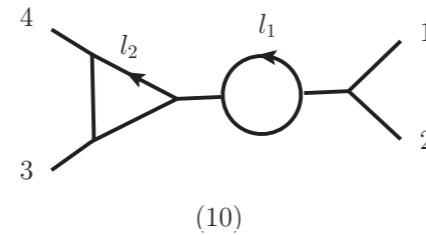
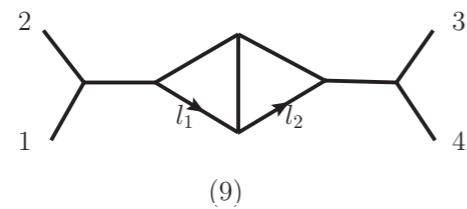
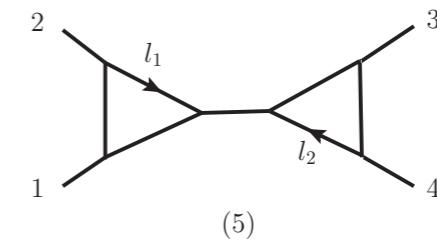
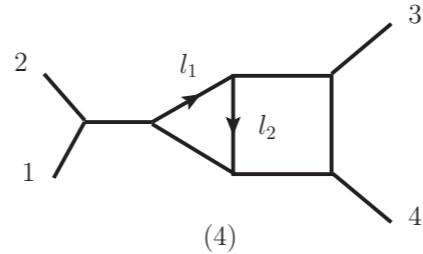
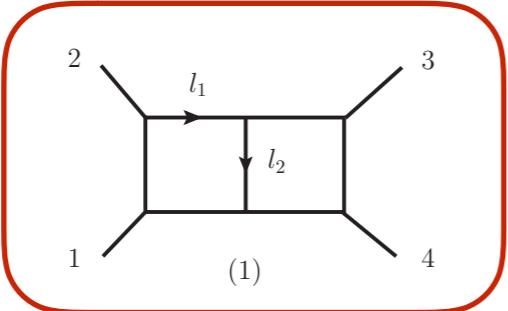
$$\Delta_5 = -\Delta_1[p_1, p_2, p_3, p_4, l_1, l_1 - l_2 + p_1 + p_2] + \Delta_1[p_1, p_2, p_4, p_3, l_1, l_1 + l_2]$$

$$\Delta_9 = -\Delta_4[p_1, p_2, p_3, p_4, l_1, l_1 - l_2] + \Delta_4[p_1, p_2, p_4, p_3, l_1, l_1 - l_2]$$

$$\Delta_{10} = -\Delta_4[p_1, p_2, p_3, p_4, l_1, l_1 + l_2 + p_1 + p_2] - \Delta_4[p_1, p_2, p_3, p_4, -l_1 - p_1 - p_2, -l_1 + l_2]$$

$$\Delta_{13} = \Delta_9 + \Delta_9[p_1, p_2, p_3, p_4, -l_1 - p_1 - p_2, l_2].$$

Ansatz of the master numerator



Consider different Lorentz structure separately:

$$\Delta_i = \Delta_i^{[1]} + \Delta_i^{[2]} + \Delta_i^{[3]}.$$

$$\Delta_1^{[1]} = (\varepsilon_1 \cdot \varepsilon_2)(\varepsilon_3 \cdot \varepsilon_4)(\sum_k c_k^{[1]} M_k^{[1]}) l_2^2$$

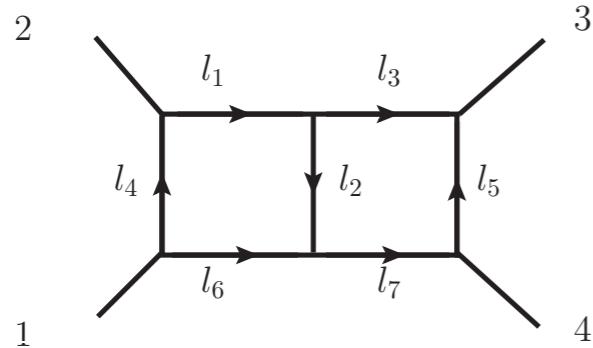
$$\Delta_1^{[2]} = \left[(\varepsilon_1 \cdot \varepsilon_2)(\sum_a c_a^{[2]} M_{1,a}^{[2]}) + (\varepsilon_3 \cdot \varepsilon_4)(\sum_b c_b^{[2]} M_{2,b}^{[2]}) \right] l_2^2$$

$$\Delta_1^{[3]} = (\sum_k c_k^{[3]} M_k^{[3]}) l_2^2$$

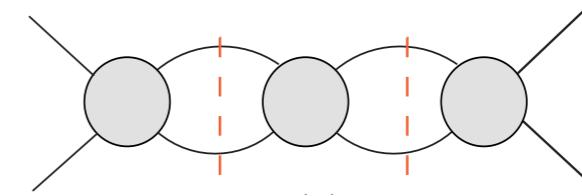
Some requirement:

- 1) do not affect other cuts,
- 2) double copy still applicable.

Solving the master numerator



$$N_i = n_i + \Delta_i$$



$$\Delta_1^{[1]} = (d-2)^2 (\varepsilon_1 \cdot \varepsilon_2) (\varepsilon_3 \cdot \varepsilon_4) l_4^2 l_2^2 l_5^2$$

$$\Delta_1^{[2]} = -4(d-2)^2 \left[(\varepsilon_1 \cdot \varepsilon_2) (\varepsilon_3 \cdot l_5) (\varepsilon_4 \cdot l_5) l_4^2 + (\varepsilon_3 \cdot \varepsilon_4) (\varepsilon_1 \cdot l_4) (\varepsilon_2 \cdot l_4) l_5^2 \right] l_2^2$$

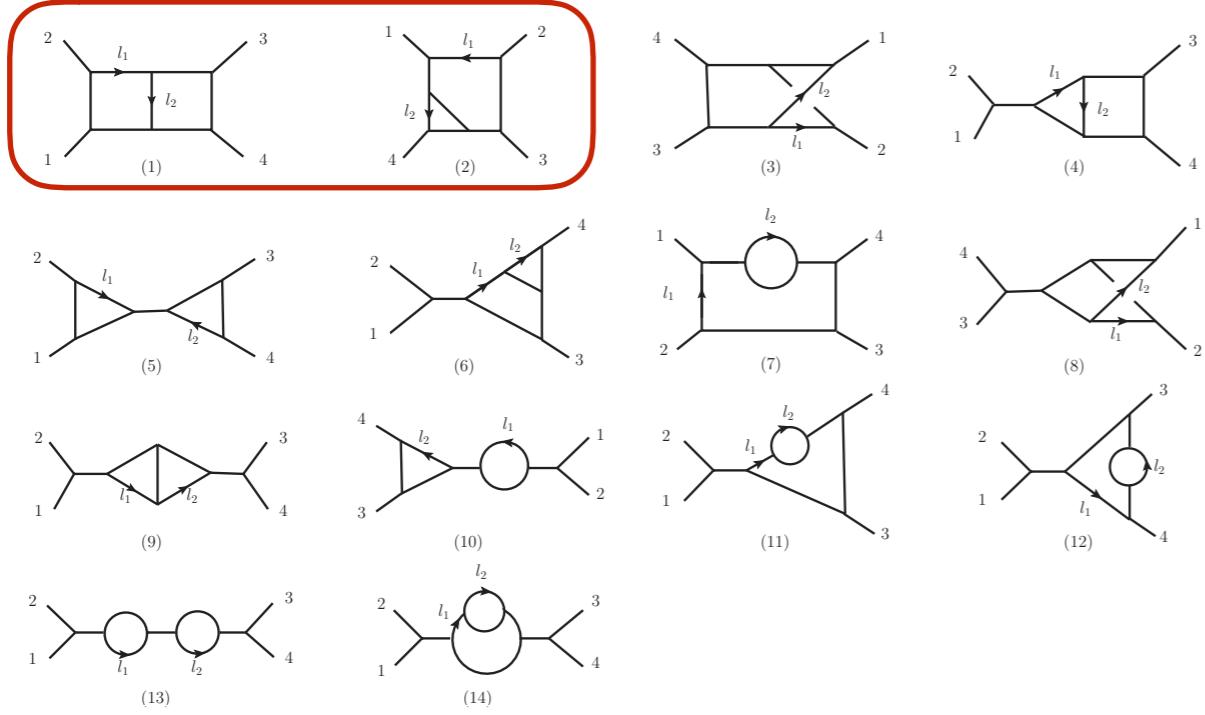
Deformation

Solution for the master numerator:

(There is a solution space with free parameters, here is a special simple choice.)

$$\begin{aligned}
 & \Delta \left[\begin{array}{c} p_2 \xrightarrow{k_2} k_3 \xleftarrow{k_3} p_3 \\ \downarrow k_5 \quad \uparrow k_7 \quad \uparrow k_6 \\ p_1 \xrightarrow{k_1} k_4 \xleftarrow{k_4} p_4 \end{array} \right] / k_7^2 = \\
 & + (d-2)^2 \left\{ (\varepsilon_1 \cdot \varepsilon_2)(\varepsilon_3 \cdot \varepsilon_4)k_5^2 k_6^2 + 16(\varepsilon_1 \cdot k_5)(\varepsilon_2 \cdot k_5)(\varepsilon_3 \cdot k_6)(\varepsilon_4 \cdot k_6) \right. \\
 & \quad \left. - 4[(\varepsilon_1 \cdot \varepsilon_2)(\varepsilon_3 \cdot k_6)(\varepsilon_4 \cdot k_6)k_5^2 + (\varepsilon_3 \cdot \varepsilon_4)(\varepsilon_1 \cdot k_5)(\varepsilon_2 \cdot k_5)k_6^2] \right\} \\
 & + (d-2)4 \left\{ - 10[(\varepsilon_1 \cdot k_6)(\varepsilon_2 \cdot k_6)(\varepsilon_3 \cdot k_5)(\varepsilon_4 \cdot k_5) + (\varepsilon_1 \cdot k_2)(\varepsilon_2 \cdot k_1)(\varepsilon_3 \cdot k_4)(\varepsilon_4 \cdot k_3)] \right. \\
 & \quad + 20[(\varepsilon_1 \cdot k_6)(\varepsilon_2 \cdot k_1)(\varepsilon_3 \cdot k_5)(\varepsilon_4 \cdot k_3) + (\varepsilon_1 \cdot k_2)(\varepsilon_2 \cdot k_6)(\varepsilon_3 \cdot k_4)(\varepsilon_4 \cdot k_5)] \\
 & \quad + 32[(\varepsilon_1 \cdot k_5)(\varepsilon_2 \cdot k_5)(\varepsilon_3 \cdot p_1)(\varepsilon_4 \cdot p_2) + (\varepsilon_1 \cdot p_3)(\varepsilon_2 \cdot p_4)(\varepsilon_3 \cdot k_6)(\varepsilon_4 \cdot k_6)] \\
 & \quad \left. + 47[(\varepsilon_1 \cdot k_4)(\varepsilon_2 \cdot k_3)(\varepsilon_3 \cdot k_4)(\varepsilon_4 \cdot k_3) + (\varepsilon_1 \cdot k_2)(\varepsilon_2 \cdot k_1)(\varepsilon_3 \cdot k_2)(\varepsilon_4 \cdot k_1)] \right\},
 \end{aligned}$$

Master topologies

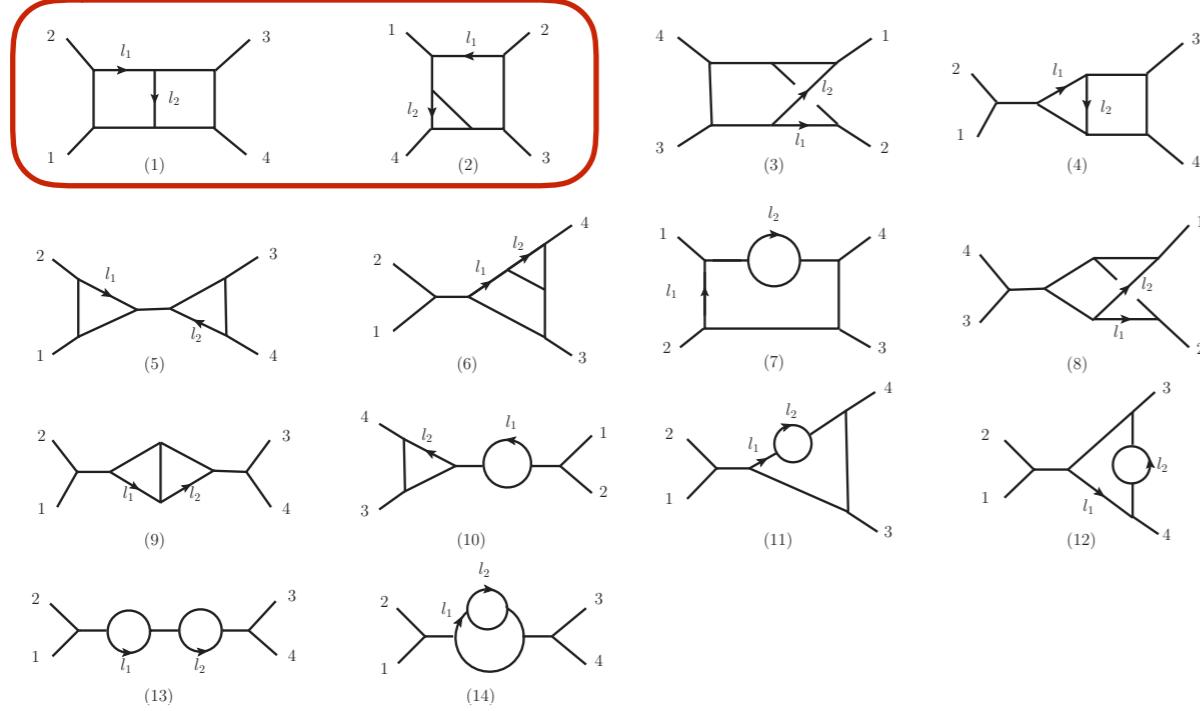


$$N_i = n_i$$



$$\begin{aligned}
 n_3 &= n_1[p_1, p_2, p_3, p_4, -l_2 - p_2, l_1 - p_2] + n_2[p_4, p_3, p_2, p_1, -l_1 - l_2 - p_3, -l_2 + p_1] \\
 n_4 &= n_1 - n_1[p_3, p_4, p_2, p_1, l_1 - l_2 + p_1 + p_2, -l_2] \\
 n_5 &= -n_1[p_1, p_2, p_3, p_4, l_1, l_1 - l_2 + p_1 + p_2] + n_1[p_1, p_2, p_4, p_3, l_1, l_1 + l_2] \\
 n_6 &= n_2[p_1, p_2, p_3, p_4, l_1 + p_1, l_2] - n_2[p_3, p_1, p_2, p_4, -l_1 - p_1 - p_2, -l_2 - p_1 - p_2 - p_3] \\
 n_7 &= -n_2[p_1, p_2, p_3, p_4, l_1, l_2] - n_2[p_1, p_2, p_3, p_4, l_1, l_1 - l_2 - p_1] \\
 n_8 &= n_3 - n_3[p_1, p_2, p_4, p_3, l_1, l_2] \\
 n_9 &= -n_4[p_1, p_2, p_3, p_4, l_1, l_1 - l_2] + n_4[p_1, p_2, p_4, p_3, l_1, l_1 - l_2] \\
 n_{10} &= -n_4[p_1, p_2, p_3, p_4, l_1, l_1 + l_2 + p_1 + p_2] - n_4[p_1, p_2, p_3, p_4, -l_1 - p_1 - p_2, -l_1 + l_2] \\
 n_{11} &= -n_4[p_1, p_2, p_3, p_4, -l_2 - p_1 - p_2, l_1 - l_2] - n_4[p_1, p_2, p_3, p_4, -l_1 + l_2 - p_1 - p_2, l_2] \\
 n_{12} &= -n_6[p_1, p_2, p_3, p_4, l_1, l_1 - l_2] - n_6[p_1, p_2, p_3, p_4, l_1, l_2 - p_1 - p_2 - p_3] \\
 n_{13} &= n_9 + n_9[p_1, p_2, p_3, p_4, -l_1 - p_1 - p_2, l_2] \\
 n_{14} &= n_9[p_1, p_2, p_3, p_4, l_1 - l_2, l_1] + n_9[p_1, p_2, p_3, p_4, -l_2 - p_1 - p_2, -l_1 - p_1 - p_2],
 \end{aligned}$$

Master topologies



$$n_3 = n_1[p_1, p_2, p_3, p_4, -l_2 - p_2, l_1 - p_2] + n_2[p_4, p_3, p_2, p_1, -l_1 - l_2 - p_3, -l_2 + p_1]$$

$$n_4 = n_1 - n_1 [p_3, p_4, p_2, p_1, l_1 - l_2 + p_1 + p_2, -l_2]$$

$$n_5 = -n_1[p_1, p_2, p_3, p_4, l_1, l_1 - l_2 + p_1 + p_2] + n_1[p_1, p_2, p_4, p_3, l_1, l_1 + l_2]$$

$$n_6 = n_2[p_1, p_2, p_3, p_4, l_1 + p_1, l_2] - n_2[p_3, p_1, p_2, p_4, -l_1 - p_1 - p_2, -l_2 - p_1 - p_2 - p_3]$$

$$n_7 = -n_2[p_1, p_2, p_3, p_4, l_1, l_2] - n_2[p_1, p_2, p_3, p_4, l_1, l_1 - l_2 - p_1]$$

$$n_8 = n_3 - n_3[p_1, p_2, p_4, p_3, l_1, l_2]$$

$$n_9 = -n_4[p_1, p_2, p_3, p_4, l_1, l_1 - l_2] + n_4[p_1, p_2, p_4, p_3, l_1, l_1 - l_2]$$

$$n_{10} = -n_4[p_1, p_2, p_3, p_4, l_1, l_1 + l_2 + p_1 + p_2] - n_4[p_1, p_2, p_3, p_4, -l_1 - p_1 - p_2, -l_1 + l_2]$$

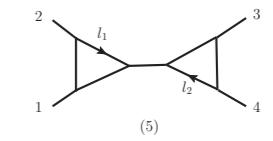
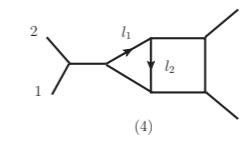
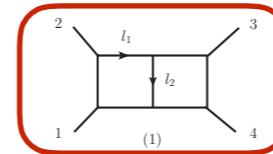
$$n_{11} = -n_4[p_1, p_2, p_3, p_4, -l_2 - p_1 - p_2, l_1 - l_2] - n_4[p_1, p_2, p_3, p_4, -l_1 + l_2 - p_1 - p_2, l_2]$$

$$n_{12} = -n_6[p_1, p_2, p_3, p_4, l_1, l_1 - l_2] - n_6[p_1, p_2, p_3, p_4, l_1, l_2 - p_1 -$$

$$n_{13} = n_9 + n_9[p_1, p_2, p_3, p_4, -l_1 - p_1 - p_2, l_2]$$

$$n_{14} = n_9[p_1, p_2, p_3, p_4, l_1 - l_2, l_1] + n_9[p_1, p_2, p_3, p_4, -l_2 - p_1 - p_2, -l_1 - p_1 - p_2],$$

$$N_i = n_i + \Delta_i$$



$$\Delta_4 = \Delta_1 - \Delta_1[p_3, p_4, p_2, p_1, l_1 - l_2 + p_1 + p_2, -l_2]$$

$$\Delta_5 = -\Delta_1[p_1, p_2, p_3, p_4, l_1, l_1 - l_2 + p_1 + p_2] + \Delta_1[p_1, p_2, p_4, p_3, l_1, l_1 + l_2]$$

$$\Delta_9 = -\Delta_4[p_1, p_2, p_3, p_4, l_1, l_1 - l_2] + \Delta_4[p_1, p_2, p_4, p_3, l_1, l_1 - l_2]$$

$$\Delta_{10} = -\Delta_4[p_1, p_2, p_3, p_4, l_1, l_1 + l_2 + p_1 + p_2] - \Delta_4[p_1, p_2, p_3, p_4, -l_1 - p_1 - p_2, -l_1 + l_2]$$

$$\Delta_{13} = \Delta_9 + \Delta_9[p_1, p_2, p_3, p_4, -l_1 - p_1 - p_2, l_2].$$

Simplicity of deformation



$$N_1 = n_1 + \Delta_1$$

Deformation

$$\begin{aligned} & \Delta \left[\begin{array}{c} p_2 \\ k_2 \\ k_3 \\ p_3 \\ \hline p_1 \\ k_5 \\ k_7 \\ k_4 \\ p_4 \end{array} \right] / k_7^2 = \\ & + (d-2)^2 \left\{ (\varepsilon_1 \cdot \varepsilon_2)(\varepsilon_3 \cdot \varepsilon_4)k_5^2 k_6^2 + 16(\varepsilon_1 \cdot k_5)(\varepsilon_2 \cdot k_5)(\varepsilon_3 \cdot k_6)(\varepsilon_4 \cdot k_6) \right. \\ & \quad \left. - 4[(\varepsilon_1 \cdot \varepsilon_2)(\varepsilon_3 \cdot k_6)(\varepsilon_4 \cdot k_6)k_5^2 + (\varepsilon_3 \cdot \varepsilon_4)(\varepsilon_1 \cdot k_5)(\varepsilon_2 \cdot k_5)k_6^2] \right\} \\ & + (d-2)4 \left\{ -10[(\varepsilon_1 \cdot k_6)(\varepsilon_2 \cdot k_6)(\varepsilon_3 \cdot k_5)(\varepsilon_4 \cdot k_5) + (\varepsilon_1 \cdot k_2)(\varepsilon_2 \cdot k_1)(\varepsilon_3 \cdot k_4)(\varepsilon_4 \cdot k_3)] \right. \\ & \quad + 20[(\varepsilon_1 \cdot k_6)(\varepsilon_2 \cdot k_1)(\varepsilon_3 \cdot k_5)(\varepsilon_4 \cdot k_3) + (\varepsilon_1 \cdot k_2)(\varepsilon_2 \cdot k_6)(\varepsilon_3 \cdot k_4)(\varepsilon_4 \cdot k_5)] \\ & \quad + 32[(\varepsilon_1 \cdot k_5)(\varepsilon_2 \cdot k_5)(\varepsilon_3 \cdot p_1)(\varepsilon_4 \cdot p_2) + (\varepsilon_1 \cdot p_3)(\varepsilon_2 \cdot p_4)(\varepsilon_3 \cdot k_6)(\varepsilon_4 \cdot k_6)] \\ & \quad \left. + 47[(\varepsilon_1 \cdot k_4)(\varepsilon_2 \cdot k_3)(\varepsilon_3 \cdot k_4)(\varepsilon_4 \cdot k_3) + (\varepsilon_1 \cdot k_2)(\varepsilon_2 \cdot k_1)(\varepsilon_3 \cdot k_2)(\varepsilon_4 \cdot k_1)] \right\}, \end{aligned} \quad (5.2)$$

Undeformed part

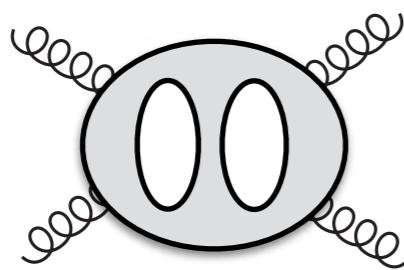
1-Numerators.m
2-SymmetryBasis.m
n1.txt
n2.txt

```
(256 - 128*d)*ep[p1,  
l1]*ep[p2, l1]*ep[p3,  
l1]*ep[p4, l1]*pp[l1, l1] +  
(-128 + 64*d)*ep[p1,  
l2]*ep[p2, l1]*ep[p3,  
l1]*ep[p4, l1]*pp[l1, l1] +  
(-9049/16 + (47261*d)/  
160)*ep[p1, p2]*ep[p2,  
l1]*ep[p3, l1]*ep[p4,  
l1]*pp[l1, l1] + (-3615/8 +  
(18363*d)/80)*ep[p1,  
p3]*ep[p2, l1]*ep[p3,  
l1]*ep[p4, l1]*pp[l1, l1] +  
(-128 + 64*d)*ep[p1,  
l1]*ep[p2, l2]*ep[p3,  
l1]*ep[p4, l1]*pp[l1, l1] +  
(128 - 64*d)*ep[p1,  
l2]*ep[p2, l2]*ep[p3,  
l1]*ep[p4, l1]*pp[l1, l1] +
```

n1.txt

Plain Text Document - 1.4 MB

Checks of the solution



$$N_i = \begin{cases} n_i + \Delta_i, & i = 1, 4, 5, 9, 10, 13, \\ n_i, & \text{others.} \end{cases}$$

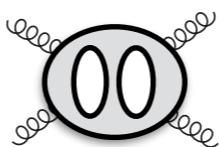
- Pass the full set of D-dimensional planar and non-planar cuts
- Three diagrams showing different types of cuts: a planar cut through three nodes, a non-planar cut through four nodes, and a non-planar cut through five nodes.
- Satisfy all CK-dual relations on cuts, so double-copy applies
- Free parameters cancel after the integral IBP reduction
- Integrated result satisfies the Catani IR formula

Outline

- Introduction
- Constructing CK-dual numerators
- New strategy of deformation
- **Summary and outlook**

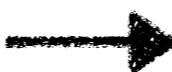
Summary and outlook

- Gauge and gravity theories are related by **double copy**.
- The key of double copy is to achieve “color-kinematics duality”.
- Finding CK-dual numerators is generally difficult, and introducing “**a simple deformation**” may solve it.



Bern, Davies and Nohle 2015

CK-duality only on cuts
initial parameters: $\sim 120,000$
after symmetry constraints: $\sim 28,000$
after cut and CK constraints: $\sim 6,300$



Duality with deformation
initial parameters: $\sim 20,000$
after CK and symmetry constraints: ~ 1400
with partial cuts + deformation : ~ 500
with remaining cut: ~ 200

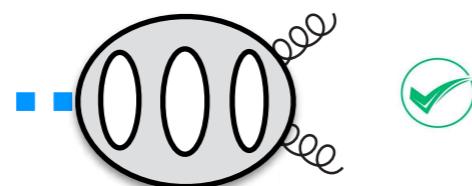
A new strategy to apply CK-duality and double-copy.

Summary and outlook

- Why so simple?

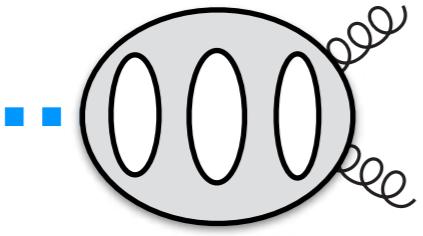
$$\begin{aligned} & \Delta \left[\begin{array}{ccccc} p_2 & k_2 & k_3 & & p_3 \\ & \downarrow & \downarrow & & \\ k_5 & & k_7 & k_6 & \\ \uparrow & & \uparrow & & \\ p_1 & k_1 & k_4 & & p_4 \end{array} \right] / k_7^2 = \\ & + (d-2)^2 \left\{ (\varepsilon_1 \cdot \varepsilon_2)(\varepsilon_3 \cdot \varepsilon_4)k_5^2 k_6^2 + 16(\varepsilon_1 \cdot k_5)(\varepsilon_2 \cdot k_5)(\varepsilon_3 \cdot k_6)(\varepsilon_4 \cdot k_6) \right. \\ & \quad \left. - 4[(\varepsilon_1 \cdot \varepsilon_2)(\varepsilon_3 \cdot k_6)(\varepsilon_4 \cdot k_6)k_5^2 + (\varepsilon_3 \cdot \varepsilon_4)(\varepsilon_1 \cdot k_5)(\varepsilon_2 \cdot k_5)k_6^2] \right\} \\ & + (d-2)4 \left\{ -10[(\varepsilon_1 \cdot k_6)(\varepsilon_2 \cdot k_6)(\varepsilon_3 \cdot k_5)(\varepsilon_4 \cdot k_5) + (\varepsilon_1 \cdot k_2)(\varepsilon_2 \cdot k_1)(\varepsilon_3 \cdot k_4)(\varepsilon_4 \cdot k_3)] \right. \\ & \quad + 20[(\varepsilon_1 \cdot k_6)(\varepsilon_2 \cdot k_1)(\varepsilon_3 \cdot k_5)(\varepsilon_4 \cdot k_3) + (\varepsilon_1 \cdot k_2)(\varepsilon_2 \cdot k_6)(\varepsilon_3 \cdot k_4)(\varepsilon_4 \cdot k_5)] \\ & \quad + 32[(\varepsilon_1 \cdot k_5)(\varepsilon_2 \cdot k_5)(\varepsilon_3 \cdot p_1)(\varepsilon_4 \cdot p_2) + (\varepsilon_1 \cdot p_3)(\varepsilon_2 \cdot p_4)(\varepsilon_3 \cdot k_6)(\varepsilon_4 \cdot k_6)] \\ & \quad \left. + 47[(\varepsilon_1 \cdot k_4)(\varepsilon_2 \cdot k_3)(\varepsilon_3 \cdot k_4)(\varepsilon_4 \cdot k_3) + (\varepsilon_1 \cdot k_2)(\varepsilon_2 \cdot k_1)(\varepsilon_3 \cdot k_2)(\varepsilon_4 \cdot k_1)] \right\}, \end{aligned}$$

- More examples: higher loop cases?

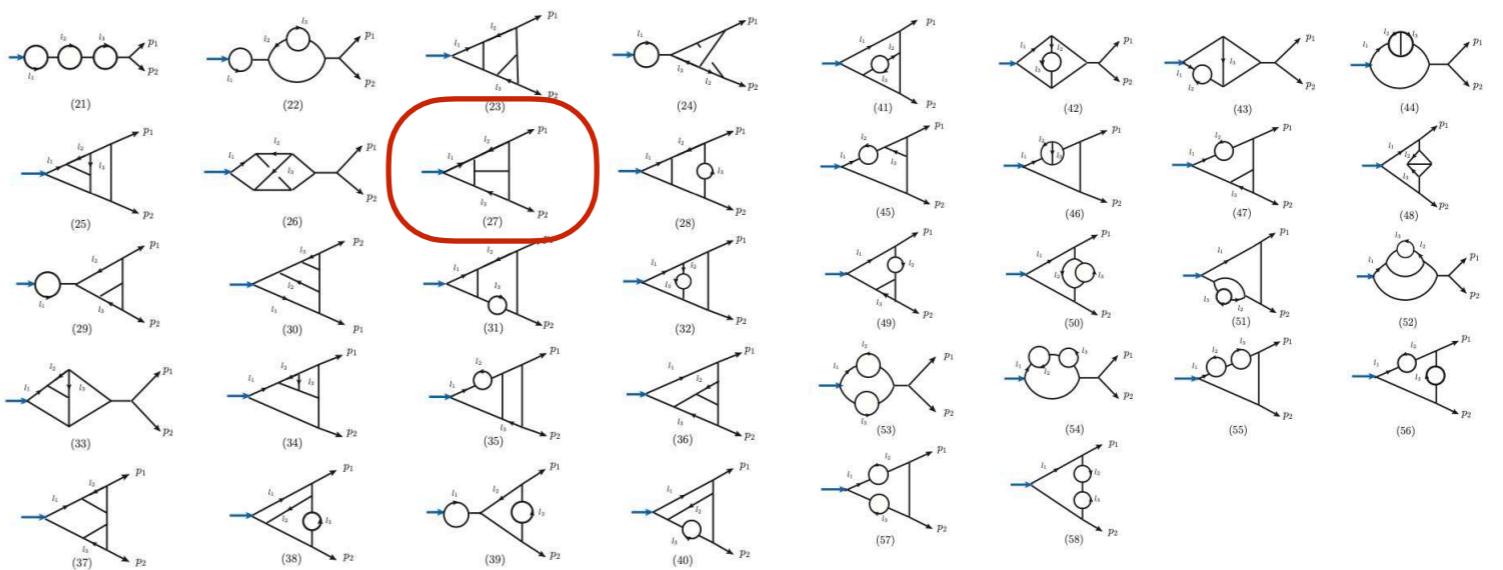
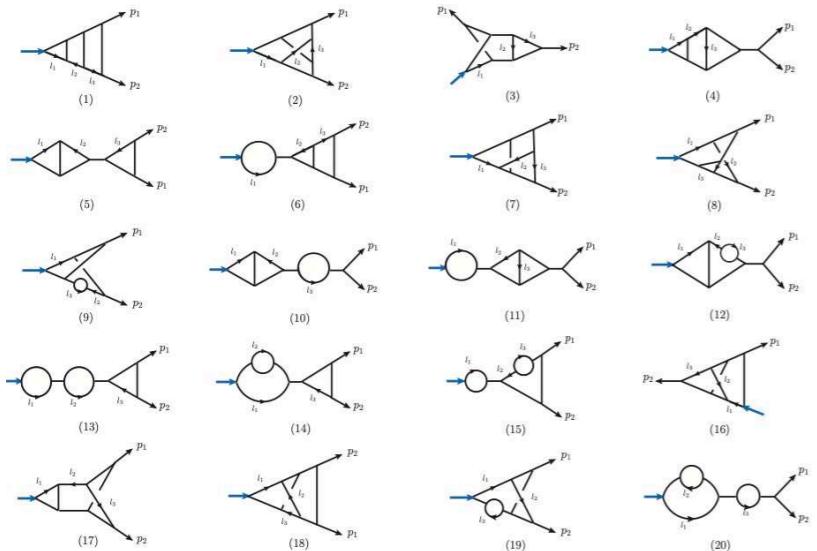
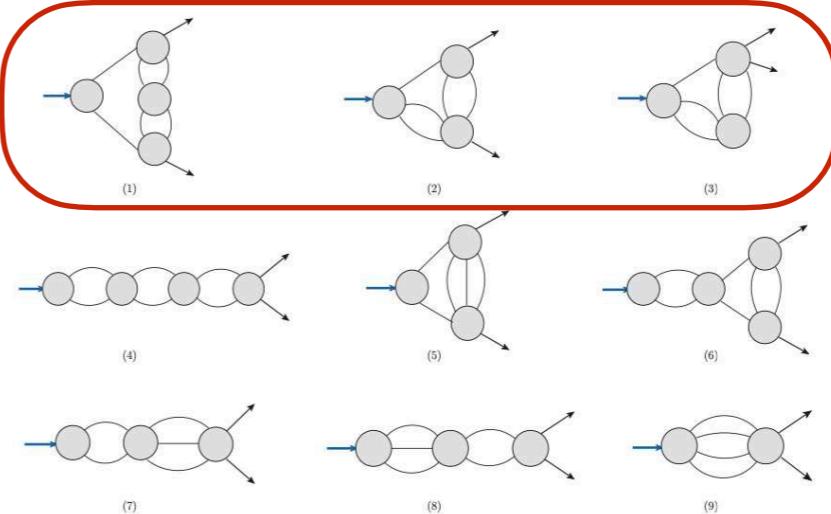


Zeyu Li, GY, Guorui Zhu in preparation

Summary and outlook



Zeyu Li, GY, Guorui Zhu in preparation

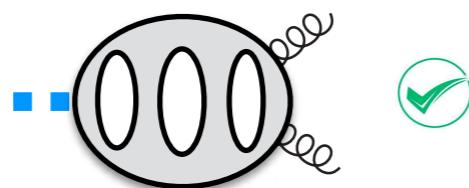


Summary and outlook

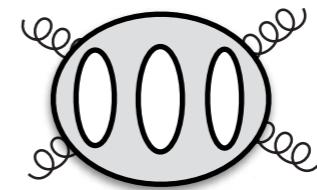
- Why so simple?

$$\begin{aligned} & \Delta \left[\begin{array}{ccccc} p_2 & k_2 & k_3 & & p_3 \\ & \downarrow & \downarrow & & \\ k_5 & & k_7 & k_6 & \\ \uparrow & & \uparrow & & \uparrow \\ p_1 & k_1 & k_4 & & p_4 \end{array} \right] / k_7^2 = \\ & + (d-2)^2 \left\{ (\varepsilon_1 \cdot \varepsilon_2)(\varepsilon_3 \cdot \varepsilon_4)k_5^2 k_6^2 + 16(\varepsilon_1 \cdot k_5)(\varepsilon_2 \cdot k_5)(\varepsilon_3 \cdot k_6)(\varepsilon_4 \cdot k_6) \right. \\ & \quad \left. - 4[(\varepsilon_1 \cdot \varepsilon_2)(\varepsilon_3 \cdot k_6)(\varepsilon_4 \cdot k_6)k_5^2 + (\varepsilon_3 \cdot \varepsilon_4)(\varepsilon_1 \cdot k_5)(\varepsilon_2 \cdot k_5)k_6^2] \right\} \\ & + (d-2)4 \left\{ -10[(\varepsilon_1 \cdot k_6)(\varepsilon_2 \cdot k_6)(\varepsilon_3 \cdot k_5)(\varepsilon_4 \cdot k_5) + (\varepsilon_1 \cdot k_2)(\varepsilon_2 \cdot k_1)(\varepsilon_3 \cdot k_4)(\varepsilon_4 \cdot k_3)] \right. \\ & \quad + 20[(\varepsilon_1 \cdot k_6)(\varepsilon_2 \cdot k_1)(\varepsilon_3 \cdot k_5)(\varepsilon_4 \cdot k_3) + (\varepsilon_1 \cdot k_2)(\varepsilon_2 \cdot k_6)(\varepsilon_3 \cdot k_4)(\varepsilon_4 \cdot k_5)] \\ & \quad + 32[(\varepsilon_1 \cdot k_5)(\varepsilon_2 \cdot k_5)(\varepsilon_3 \cdot p_1)(\varepsilon_4 \cdot p_2) + (\varepsilon_1 \cdot p_3)(\varepsilon_2 \cdot p_4)(\varepsilon_3 \cdot k_6)(\varepsilon_4 \cdot k_6)] \\ & \quad \left. + 47[(\varepsilon_1 \cdot k_4)(\varepsilon_2 \cdot k_3)(\varepsilon_3 \cdot k_4)(\varepsilon_4 \cdot k_3) + (\varepsilon_1 \cdot k_2)(\varepsilon_2 \cdot k_1)(\varepsilon_3 \cdot k_2)(\varepsilon_4 \cdot k_1)] \right\}, \end{aligned}$$

- More examples: higher loop cases?

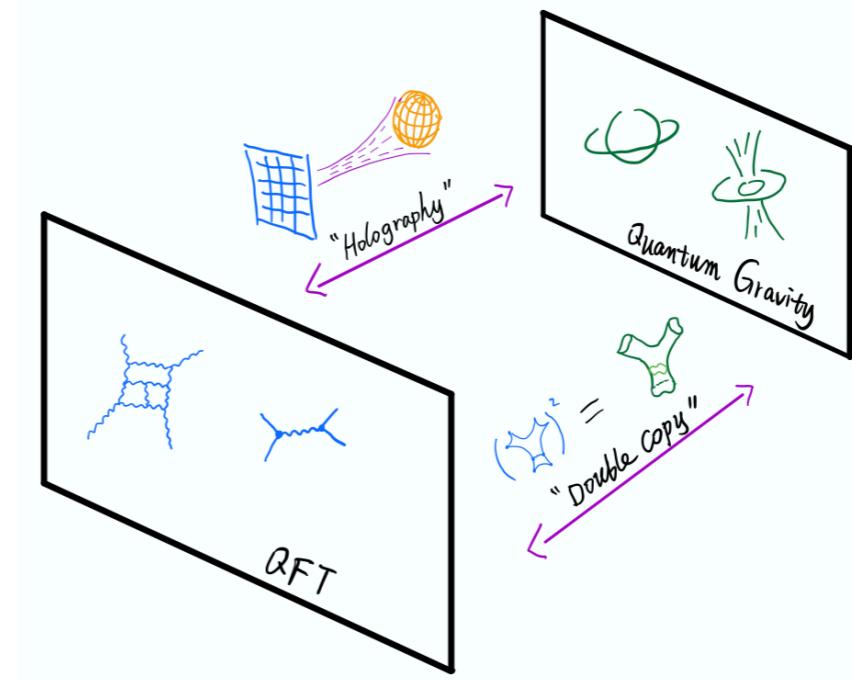
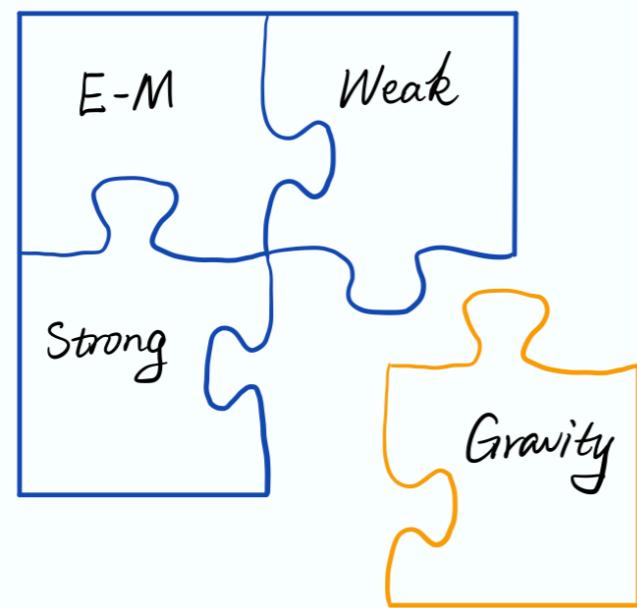


Zeyu Li, GY, Guorui Zhu in preparation



Towards 3-loop Einstein gravity?

- Are there underlying structures for the deformation?



Thank you for your attention!

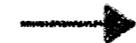


Back up slides

From YM to gravity

If the gauge amplitude **satisfies CK duality**, one can directly construct gravity amplitude:

$$A_4(1,2,3,4) = \frac{c_s n_s}{s} + \frac{c_t n_t}{t} + \frac{c_u n_u}{u}$$



$$M_4(1,2,3,4) = \frac{n_s n_s}{s} + \frac{n_t n_t}{t} + \frac{n_u n_u}{u}$$

Gauge invariance
 $\varepsilon_i^\mu \rightarrow \varepsilon_i^\mu + p_i^\mu$

CK-duality

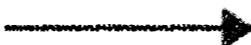
Diffeomorphism invariance
 $\varepsilon_i^{\mu\nu} \rightarrow \varepsilon_i^{\mu\nu} + p_i^{(\mu} q^{\nu)}$

$$n_i \rightarrow n_i + \delta_i,$$

$$\delta_i = n_i|_{\varepsilon_j \rightarrow p_j}$$

$$\sum_i \frac{c_i \delta_i}{D_i} = 0$$

$$c_i = c_j + c_k$$



$$\sum_i \frac{n_i \delta_i}{D_i} = 0$$

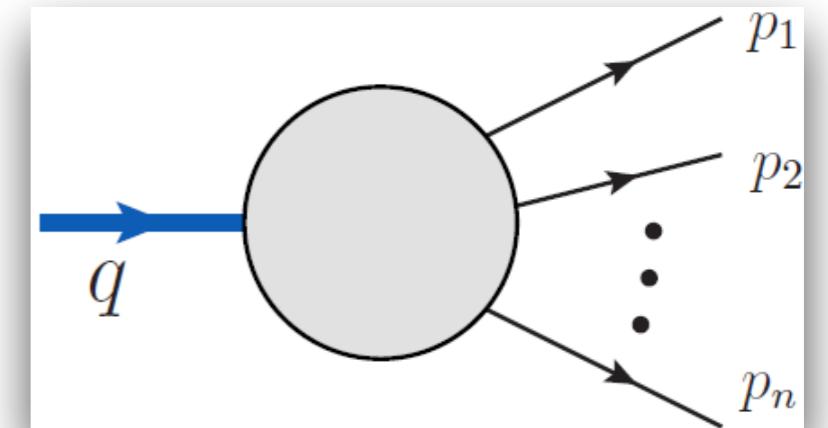
$$n_i = n_j + n_k$$

Form Factors

Matrix element of on-shell states and a local operators:

$$\begin{aligned} F_{n,\mathcal{O}}(1, \dots, n) &= \int d^4x e^{-iq \cdot x} \langle p_1 \dots p_n | \mathcal{O}(x) | 0 \rangle \\ &= \delta^{(4)}\left(\sum_{i=1}^n p_i - q\right) \langle p_1 \dots p_n | \mathcal{O}(0) | 0 \rangle \end{aligned}$$

(work in momentum space)



$$q = \sum_i p_i, \quad q^2 \neq 0$$

$$\langle p_1 p_2 \dots p_n | 0 \rangle$$

Amplitudes



Form Factors

$$\langle \mathcal{O}_1 \mathcal{O}_2 \dots \mathcal{O}_n \rangle$$

Correlation functions

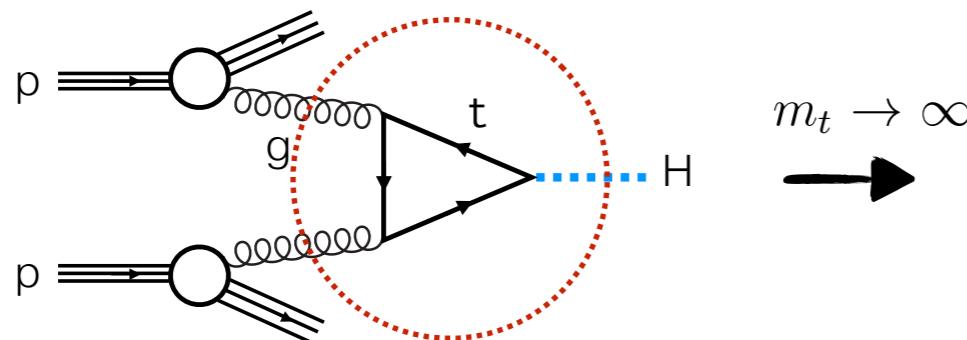
Operators

Gauge invariant operators are important in QFT.

- Anomalous dimensions (spectrum of hadrons, RG, OPE, ...)
- Correlation functions (e.g., EEC)

Local operators also appear as vertices in EFT Lagrangian.
For example: Higgs EFT obtained by integrating Top quark loop:

Wilczek, 1977; Shifman et.al., 1979,

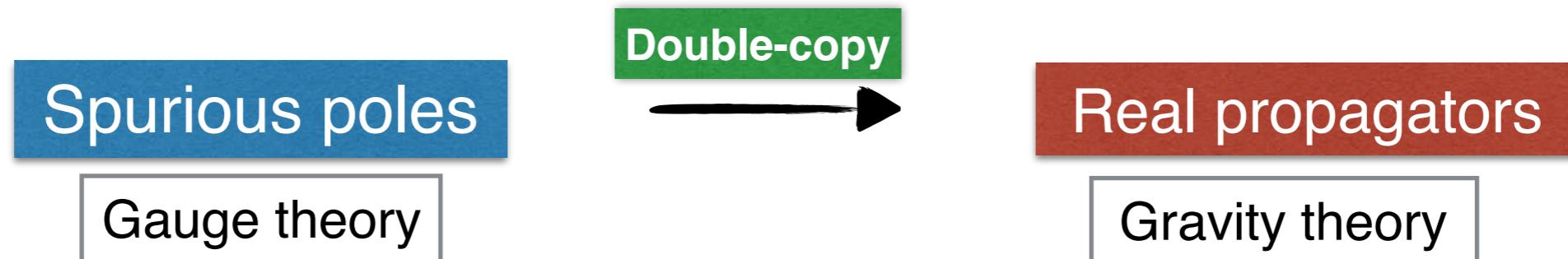


$$\mathcal{L}_{\text{eff}} = \hat{C}_0 H \mathcal{O}_{4;0} + \sum_{k=1}^{\infty} \frac{1}{m_t^{2k}} \sum_i \hat{C}_i H \mathcal{O}_{4+2k;i}$$

Double copy of form factor



- An surprising new mechanism for form factors:



- Hidden “factorization” relations of gauge form factors

$$\vec{v} \cdot \vec{\mathcal{F}}_n \Big|_{\text{spurious pole}} = \mathcal{F}_m \times \mathcal{A}_{n+2-m}$$

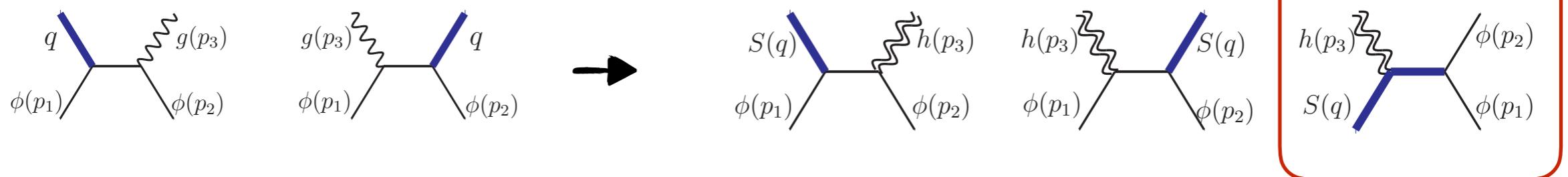
Example: 3-point form factor

$$\mathcal{G}_3 = \frac{(N_1^{\text{CK}})^2}{s_{23}} + \frac{(N_2^{\text{CK}})^2}{s_{13}} = \frac{s_{13}s_{23}}{s_{13} + s_{23}} \left(\mathcal{F}_3(1^\phi, 3^g, 2^\phi) \right)^2$$

There is a nice factorization behavior at the new pole:

$$s_{13} + s_{23} = q^2 - s_{12} = 0$$

$$\text{Res} [\mathcal{G}_3]_{s_{12}=q^2} = (\epsilon_3 \cdot q)^2 = (\mathcal{F}_2(1^\phi, 2^\phi))^2 \times (\mathcal{A}_3(\mathbf{q}_2^S, 3^g, -q^S))^2$$



A new graph
in gravity

A new type of hidden relations

For gauge-theory form factors:

$$\vec{v} \cdot \vec{\mathcal{F}}_n \Big|_{\text{spurious pole}} = \mathcal{F}_m \times \mathcal{A}_{n+2-m}$$

“Factorization” at spurious poles

$$[s_{42}\mathcal{F}_4(1, 3, 4, 2) + (s_{42} + s_{43})\mathcal{F}_4(1, 4, 3, 2)] \Big|_{s_{123}=q^2} = \mathcal{F}_3(1^\phi, 3^g, 2^\phi) \mathcal{A}_3(\mathbf{q}_3^S, 4^g, -q^S)$$

The relation is reminiscent of the BCJ relation for amplitudes:

$$s_{42}\mathcal{A}_4(1, 3, 4, 2) + (s_{42} + s_{43})\mathcal{A}_4(1, 4, 3, 2) = 0$$